

1. a. (5pts) In \mathbb{R}^5 , you are given 3 vectors

$$v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, v_2 = \begin{pmatrix} 3 \\ 1 \\ -1 \\ 0 \\ 2 \end{pmatrix}, v_3 = \begin{pmatrix} 7 \\ -2 \\ 1 \\ 1 \\ 3 \end{pmatrix}$$

Apply Gram-Schmidt (Orthogonalization) Process to find an orthonormal basis of $\text{Span}\{v_1, v_2, v_3\}$.

$$u_1 = v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, u_2 = v_2 - \frac{\langle u_1, v_2 \rangle}{\langle u_1, u_1 \rangle} u_1 = \begin{pmatrix} 3 \\ 1 \\ -1 \\ 0 \\ 2 \end{pmatrix} - \frac{5}{5} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ -2 \\ -1 \\ 1 \end{pmatrix}$$

$$u_3 = v_3 - \frac{\langle u_1, v_3 \rangle}{\langle u_1, u_1 \rangle} u_1 - \frac{\langle u_2, v_3 \rangle}{\langle u_2, u_2 \rangle} u_2 = \begin{pmatrix} 7 \\ -2 \\ 1 \\ 1 \\ 3 \end{pmatrix} - \frac{10}{5} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \frac{14}{10} \begin{pmatrix} 2 \\ 0 \\ -2 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ -4 \\ -1 \\ -1 \\ 1 \end{pmatrix} - \frac{1}{5} \begin{pmatrix} 14 \\ 0 \\ -14 \\ -2 \\ 14 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 11 \\ -20 \\ 9 \\ 2 \\ 2 \end{pmatrix}$$

$\{u_1, u_2, u_3\}$ is an orthogonal basis.

To change it to an orthonormal basis, we divide them by their lengths.

$$\Rightarrow \frac{1}{\sqrt{5}} u_1, \frac{1}{\sqrt{10}} u_2, \frac{1}{\sqrt{11^2+20^2+9^2+2^2+2^2}} \begin{pmatrix} 11 \\ -20 \\ 9 \\ 2 \\ 2 \end{pmatrix}$$

b. (8pts) Solve the least-squares problem $x \approx b$

$$Ax = b \text{ where } A = \begin{pmatrix} 1 & 3 & 7 \\ 1 & 1 & -2 \\ 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 3 \end{pmatrix}, b = \begin{pmatrix} 2 \\ 1 \\ 2 \\ -5 \\ 5 \end{pmatrix}$$

in two different ways. (Hint. One way is to use the result of a. For any theorems you might use, please state them correctly, though you do not need to prove the theorems.)

① A least-square solution x is the vector which makes Ax be the orthogonal projection of b .

If $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$, then b 's orthogonal projection using an orthogonal basis $\left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ -2 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 11 \\ -20 \\ 9 \\ 2 \\ 2 \end{pmatrix} \right\}$ is $\frac{5}{5} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} + \frac{10}{10} \begin{pmatrix} 2 \\ 0 \\ -2 \\ -1 \\ 1 \end{pmatrix} + \frac{0}{610} \begin{pmatrix} 11 \\ -20 \\ 9 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -1 \\ 0 \\ 2 \end{pmatrix}$

Hence, $x = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$.

② We can find the answer using the normal equation.

$$A^T A x = A^T b$$

$$A^T A = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 3 & 1 & -1 & 0 & 2 \\ 7 & -2 & 1 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 3 & 7 \\ 1 & 1 & -2 \\ 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 5 & 5 & 10 \\ 5 & 15 & 24 \\ 10 & 24 & 64 \end{pmatrix}$$

$$A^T b = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 3 & 1 & -1 & 0 & 2 \\ 7 & -2 & 1 & 1 & 3 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 2 \\ -5 \\ 5 \end{pmatrix} = \begin{pmatrix} 5 \\ 15 \\ 24 \end{pmatrix} \Rightarrow x = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

2. Define $B = \left\{ \begin{pmatrix} 5 \\ 5 \\ -3 \end{pmatrix}, \begin{pmatrix} -3 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \right\}$.

a. (3pts) Find the inverse matrix of P where

$$P = \begin{pmatrix} 5 & -3 & 1 \\ 5 & 2 & 2 \\ -3 & 0 & -1 \end{pmatrix}$$

$$\begin{pmatrix} 5 & -3 & 1 & 0 & 0 \\ 5 & 2 & 2 & 0 & 0 \\ -3 & 0 & -1 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 5 & -3 & 1 & 1 & 0 & 0 \\ 0 & 5 & 1 & -1 & 1 & 0 \\ -3 & 0 & -1 & 0 & 0 & 1 \end{pmatrix} \sim \begin{pmatrix} -3 & 0 & -1 & 0 & 0 & 1 \\ 0 & 5 & 1 & -1 & 1 & 0 \\ 5 & -3 & 1 & 1 & 0 & 0 \end{pmatrix}$$

$$\sim \begin{pmatrix} -1 & 0 & -\frac{1}{3} & 0 & 0 & \frac{1}{3} \\ 0 & 1 & \frac{1}{5} & -\frac{1}{5} & \frac{1}{5} & 0 \\ 5 & -3 & 1 & 1 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & \frac{1}{3} & 0 & 0 & -\frac{1}{3} \\ 0 & 1 & \frac{1}{5} & -\frac{1}{5} & \frac{1}{5} & 0 \\ 0 & 0 & \frac{2}{3} & 1 & -\frac{5}{3} & \frac{2}{3} \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & \frac{1}{3} & 0 & 0 & -\frac{1}{3} \\ 0 & 1 & \frac{1}{5} & -\frac{1}{5} & \frac{1}{5} & 0 \\ 0 & 0 & -\frac{1}{15} & \frac{2}{3} & \frac{3}{5} & \frac{5}{3} \end{pmatrix}$$

b. (4pts) Find the B -coordinate of $\begin{pmatrix} 4 \\ 2 \\ -11 \end{pmatrix}$.

$$= \begin{pmatrix} 2 & 3 & 8 \\ 1 & 2 & 5 \\ -6 & -9 & -25 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \\ -11 \end{pmatrix} = \begin{pmatrix} -74 \\ -47 \\ 233 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & 2 & 3 & 8 \\ 0 & 1 & 0 & 1 & 2 & 5 \\ 0 & 0 & 1 & -6 & -9 & -25 \end{pmatrix} \Rightarrow P^{-1} = \begin{pmatrix} 2 & 3 & 8 \\ 1 & 2 & 5 \\ -6 & -9 & -25 \end{pmatrix}$$

c. (5pts) Let a linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the map sending x to Ax where

$$A = \begin{pmatrix} 12 & 15 & 40 \\ 10 & 17 & 40 \\ -6 & -9 & -22 \end{pmatrix}$$

Find the B -matrix for T .

$$P^{-1}AP = \begin{pmatrix} 2 & 3 & 8 \\ 1 & 2 & 5 \\ -6 & -9 & -25 \end{pmatrix} \begin{pmatrix} 12 & 15 & 40 \\ 10 & 17 & 40 \\ -6 & -9 & -22 \end{pmatrix} \begin{pmatrix} 5 & -3 & 1 \\ 5 & 2 & 2 \\ -3 & 0 & -1 \end{pmatrix}$$

As long as you find that $A \begin{pmatrix} 5 \\ 5 \\ -3 \end{pmatrix} = \begin{pmatrix} 15 \\ 15 \\ -9 \end{pmatrix} = 3 \begin{pmatrix} 5 \\ 5 \\ -3 \end{pmatrix}$ (this equality)

$$= P^{-1} \begin{pmatrix} 15 & -6 & 2 \\ 15 & 4 & 4 \\ -9 & 0 & -2 \end{pmatrix} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

and $\begin{pmatrix} -6 \\ 4 \\ 8 \end{pmatrix} = 2 \begin{pmatrix} -3 \\ 2 \\ 4 \end{pmatrix}$, ... you do not need calculations for this multiplication. Since, $P^{-1}AP = D$ for D st its diagonal entries are eigenvalues.

3. Write "TRUE" if the statement is always true, "FALSE" if it is sometimes false. *No explanations are needed.*

a. (2pts) Given a subspace W of V , the orthogonal projection map from V to W is a one-to-one linear transformation.

False. (It does not need to be one-to-one.)

b. (2pts) The orthogonal complement of the null space of A is the same as the column space of A if A is symmetric.

True. $(\text{Col } A)^\perp = \text{Row } A = \text{Col } (A^T) = \text{Col } (A)$.

c. (2pts) If the orthogonal complement of the null space of A is the same as the column space of A , then A is symmetric.

False. (Every invertible matrix can be a counterexample.)

d. (2pts) The quadratic form Q on \mathbb{R}^3 defined as

$$Q(x_1, x_2, x_3) = 3x_1^2 + 2x_2^2 + x_3^2 + 4x_1x_2 - 4x_2x_3$$

is an indefinite quadratic form.

~~$\begin{pmatrix} 3 & 2 & 0 \\ 2 & 2 & -2 \\ 0 & -2 & 1 \end{pmatrix}$~~ $\left(\begin{array}{l} Q(1, 0, 0) = 3 > 0 \\ Q(0, 1, 1) = -1 < 0. \end{array} \right)$ True.

e. (2pts) Let a vector space \mathbb{R}^3 be equipped with an inner product defined as

$$\langle (x_1, x_2, x_3), (y_1, y_2, y_3) \rangle = (x_1 + 2x_2)(y_1 + 2y_2) + x_3y_3$$

In this inner product space, $(1, 0, 0)$ and $(0, 1, 0)$ are orthogonal still.

False. $\langle (1, 0, 0), (0, 1, 0) \rangle = (1)(2) + 0 = 2 \neq 0$.

f. (2pts) A square matrix A is invertible if and only if 0 is not an eigenvalue of A .

True. $(A \text{ invertible} \Leftrightarrow \det A \neq 0)$
 $\Leftrightarrow \det(A - 0 \cdot I) \neq 0$

4. (8pts) Find the maximum and minimum values of

$$Q(x_1, x_2, x_3) = -x_1^2 + x_2^2 - 7x_3^2 - 8x_1x_2 - 8x_2x_3$$

subject to the constraint

$$x_1^2 + x_2^2 + x_3^2 = 1$$

The matrix of the quadratic form Q , is

$$A = \begin{pmatrix} -1 & -4 & 0 \\ -4 & 1 & -4 \\ 0 & -4 & -7 \end{pmatrix}$$

$$\chi_A(\lambda) = \det(A - \lambda I)$$

$$= \det \begin{pmatrix} -1-\lambda & -4 & 0 \\ -4 & 1-\lambda & -4 \\ 0 & -4 & -7-\lambda \end{pmatrix} = (-1-\lambda)((-1-\lambda)(-7-\lambda) - 16) - (-4)(-4)(-7-\lambda)$$

$$= -(\lambda+1)(\lambda^2+6\lambda-7-16) + 16\lambda + 112$$

$$= -(\lambda^3+7\lambda^2-17\lambda-23) + 16\lambda + 112$$

$$= -\lambda^3 - 7\lambda^2 + 33\lambda + 135$$

plug in ~~5~~ first:

$$5 \cdot (25 - 35 + 33 + 27) = 5 \cdot 0$$

$$= -(\lambda-5)(\lambda^2+12\lambda+27)$$

$$= -(\lambda-5)(\lambda+3)(\lambda+9)$$

So, the maximum is 5
minimum is -9.

5. Let A be

$$\begin{pmatrix} 3 & -4 & -4 \\ 2 & 1 & -4 \\ -2 & 0 & 5 \end{pmatrix}$$

whose characteristic polynomial $\chi_A(\lambda)$ is $-(\lambda - 1)(\lambda - 3)(\lambda - 5)$.

a. (5pts) Find 3 linearly independent eigenvectors and, using them, find a diagonal matrix D and an invertible matrix P such that

We have 3 distinct eigenvalues \Rightarrow we can find 3 linearly independent eigenvectors. $P^{-1}AP = D$

$$\text{Nul}(A - I) = \text{Nul} \begin{pmatrix} 2 & -4 & -4 \\ 2 & 0 & -4 \\ -2 & 0 & 4 \end{pmatrix} = \text{Span} \left\{ \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\text{Nul}(A - 3I) = \text{Nul} \begin{pmatrix} 0 & -4 & -4 \\ 2 & -2 & -4 \\ -2 & 0 & 2 \end{pmatrix} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$$\text{Nul}(A - 5I) = \text{Nul} \begin{pmatrix} -2 & -4 & -4 \\ 2 & -4 & -4 \\ -2 & 0 & 0 \end{pmatrix} = \text{Span} \left\{ \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$$\therefore \text{If we let } P \text{ be } \begin{pmatrix} 2 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & -1 \end{pmatrix}, \text{ then } P^{-1}AP = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{pmatrix} = D.$$

b. (6pts) You have found only one pair of (D, P) in problem a. Find all possible D 's. For each D , find one corresponding invertible matrix P such that $P^{-1}AP = D$.

For the equation $P^{-1}AP = D$ to be true, columns of P should be eigenvectors of A or the zero vector. However, since P is invertible they should be eigenvectors. As a result, D 's diagonal entries should be corresponding eigenvalues. Hence there could be 6 D 's.

$$\textcircled{1} D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{pmatrix}, P = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & -1 \end{pmatrix} \quad \textcircled{2} D = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{pmatrix}, P = \begin{pmatrix} 1 & 2 & 0 \\ -1 & 0 & 1 \\ 1 & 1 & -1 \end{pmatrix}$$

$$\textcircled{3} D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{pmatrix}, P = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & -1 & 1 \end{pmatrix} \quad \textcircled{4} D = \begin{pmatrix} 5 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}, P = \begin{pmatrix} 0 & 2 & 1 \\ 1 & 0 & -1 \\ -1 & 1 & 1 \end{pmatrix}$$

$$\textcircled{5} D = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{pmatrix}, P = \begin{pmatrix} 0 & 0 & 2 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} \quad \textcircled{6} D = \begin{pmatrix} 5 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix}, P = \begin{pmatrix} 0 & 1 & 2 \\ 1 & -1 & 0 \\ -1 & 1 & 1 \end{pmatrix}$$

6. Let T be a transformation from \mathbb{P}_2 to \mathbb{R}^3 such that

$$T(p(t)) = \begin{pmatrix} p(0) \\ p(1) \\ p(2) \end{pmatrix}$$

a. (3pts) Show that T is a linear transformation.

$$\textcircled{1} T(p+q) = \begin{pmatrix} (p+q)(0) \\ (p+q)(1) \\ (p+q)(2) \end{pmatrix} = \begin{pmatrix} p(0) \\ p(1) \\ p(2) \end{pmatrix} + \begin{pmatrix} q(0) \\ q(1) \\ q(2) \end{pmatrix} = T(p) + T(q)$$

$$\textcircled{2} T(cp) = \begin{pmatrix} (cp)(0) \\ (cp)(1) \\ (cp)(2) \end{pmatrix} = \begin{pmatrix} c p(0) \\ c p(1) \\ c p(2) \end{pmatrix} = c \begin{pmatrix} p(0) \\ p(1) \\ p(2) \end{pmatrix} = c \cdot T(p)$$

By $\textcircled{1}, \textcircled{2}$, T is a linear transformation

b. (6pts) Find $\ker T$. What is the dimension of $\ker T$? Conclude that $\text{im } T$ is a 3-dimensional subspace of \mathbb{R}^3 so that $\text{im } T = \mathbb{R}^3$. (Regard T as a linear transformation from \mathbb{P}_2 (3-dimensional vector space) to $\text{im } T$.)

$$\ker T = \left\{ p(t) \in \mathbb{P}_2 : T(p(t)) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\} \text{ by definition.}$$

$$= \left\{ p(t) \in \mathbb{P}_2 : p(0) = 0, p(1) = 0, p(2) = 0 \right\}$$

~~Since \mathbb{P}_2~~ Let $p(t) \in \mathbb{P}_2$ satisfy $p(0) = p(1) = p(2) = 0$. Then, $c = 0$ ($p(0) = 0$)
 $at^2 + bt + c = 0$ ($p(1) = 0$) $\Rightarrow a + b + c = 0$
 $4a + 2b + c = 0$ ($p(2) = 0$)
 $\Rightarrow a = b = c = 0$.

$$= \left\{ 0 \cdot t^2 + 0 \cdot t + 0 \right\} = \{0\}$$

Hence, T is one-to-one. Therefore, $\text{im } T$ has its dimension as same as the dimension of \mathbb{P}_2 . Therefore, it has dimension 3. The only 3-dimensional subspace of a 3-dimensional space is itself.

c. (6pts) Prove that T is one-to-one and onto. And then interpret the fact as following: $\Rightarrow \text{im } T = \mathbb{R}^3$.
 A polynomial of degree at most 2 is uniquely determined by three points $(0, p(0))$, $(1, p(1))$, and $(2, p(2))$.

In problem b, we have shown that T is one-to-one, and since $\text{im } T = \mathbb{R}^3$, it is onto.

This implies that if $T(p(t)) = T(q(t))$, then $p(t) = q(t)$.
 as well as that for every pair of three points $(0, p(0))$, $(1, p(1))$, $(2, p(2))$
 (or three numbers) $p(0), p(1), p(2)$

there exists a polynomial $p(t)$ s.t. $T(p(t)) = \begin{pmatrix} p(0) \\ p(1) \\ p(2) \end{pmatrix}$.

It means that $p(t)$ and $T(p(t))$ have one-to-one correspondence.

Hence, $p(t)$ is uniquely determined by three points $(0, p(0))$, $(1, p(1))$, $(2, p(2))$.