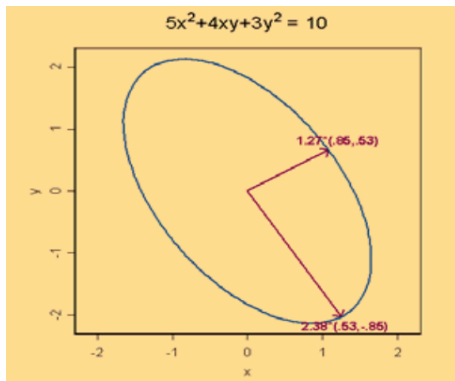


## §7.1 Diagonalization of Symmetric Matrices

Equation for an ellipse:  $5x^2 + 4xy + 3y^2 = 10$ ,

In matrix form:  $\mathbf{x}^T A \mathbf{x} = 10$ ,  $\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix}$ ,  $A = \begin{bmatrix} 5 & 2 \\ 2 & 3 \end{bmatrix}$ .



Find the major/minor axes and their lengths.

Equation for an ellipse:  $\mathbf{x}^T A \mathbf{x} = 10$ ,  $\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix}$ ,  $A = \begin{bmatrix} 5 & 2 \\ 2 & 3 \end{bmatrix}$ .

► Eigenvalues of  $A$ :  $\lambda_1 = 4 - \sqrt{5}$ ,  $\lambda_2 = 4 + \sqrt{5}$ ; eigenvectors are

$$A \mathbf{v}_1 = \lambda_1 \mathbf{v}_1, \quad \mathbf{v}_1 = \begin{bmatrix} -2 \\ \sqrt{5} + 1 \end{bmatrix}, \quad A \mathbf{v}_2 = \lambda_2 \mathbf{v}_2, \quad \mathbf{v}_2 = \begin{bmatrix} \sqrt{5} + 1 \\ 2 \end{bmatrix}.$$

►  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are orthogonal:  $\mathbf{v}_1^T \mathbf{v}_2 = 0$  :

►  $Q \stackrel{\text{def}}{=} \left( \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}, \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|} \right)$  is orthogonal matrix:  $Q^{-1} = Q^T$ .

$$A = Q \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} Q^T. \quad \text{Change coordinates: } \begin{bmatrix} u \\ v \end{bmatrix} \stackrel{\text{def}}{=} Q^T \mathbf{x}$$

$$10 = \mathbf{x}^T A \mathbf{x} = \begin{bmatrix} u \\ v \end{bmatrix}^T \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = (4 - \sqrt{5}) u^2 + (4 + \sqrt{5}) v^2.$$

► major/minor axes = Columns of  $Q$ ,

$$\text{axis lengths} = \sqrt{\frac{10}{4 - \sqrt{5}}}, \sqrt{\frac{10}{4 + \sqrt{5}}}.$$

# Diagonalization of Symmetric Matrices

Let  $A \in \mathcal{R}^{n \times n}$  be a symmetric matrix.

**Thm 1.** Any two real eigenvectors pertaining to two distinct real eigenvalues of  $A$  are orthogonal.

# Diagonalization of Symmetric Matrices

Let  $A \in \mathcal{R}^{n \times n}$  be a symmetric matrix.

**Thm 1.** Any two real eigenvectors pertaining to two distinct real eigenvalues of  $A$  are orthogonal.

PROOF: Let  $\lambda_1$  and  $\lambda_2$  be distinct eigenvalues of  $A$ , with

$$A \mathbf{v}_1 = \lambda_1 \mathbf{v}_1, \quad A \mathbf{v}_2 = \lambda_2 \mathbf{v}_2.$$

$$\text{so that } \lambda_1 \mathbf{v}_2^T \mathbf{v}_1 = \mathbf{v}_2^T (A \mathbf{v}_1) = (A \mathbf{v}_2)^T \mathbf{v}_1 = \lambda_2 \mathbf{v}_2^T \mathbf{v}_1.$$

This implies  $(\lambda_2 - \lambda_1) \mathbf{v}_2^T \mathbf{v}_1 = 0$ , or  $\mathbf{v}_2^T \mathbf{v}_1 = 0$ .

# Diagonalization of Symmetric Matrices: Main Theorem

**Thm:** A matrix  $A \in \mathbb{R}^n$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^n$  and an orthogonal matrix  $Q$  so that

$$A = Q D Q^T = Q \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{pmatrix} Q^T.$$

# Diagonalization of Symmetric Matrices: Main Theorem

**Thm:** A matrix  $A \in \mathbb{R}^n$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^n$  and an orthogonal matrix  $Q$  so that

$$A = Q D Q^T = Q \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{pmatrix} Q^T.$$

**Note:** Assume  $A = Q D Q^T$  with  $Q = (\mathbf{q}_1, \dots, \mathbf{q}_n)$  orthogonal, and  $D = \mathbf{diag}(d_1, \dots, d_n)$  diagonal. Then  $A Q = Q D$ ,

$$A (\mathbf{q}_1, \dots, \mathbf{q}_n) = (\mathbf{q}_1, \dots, \mathbf{q}_n) \mathbf{diag}(d_1, \dots, d_n) = (d_1 \mathbf{q}_1, \dots, d_n \mathbf{q}_n).$$

► Therefore

$$A \mathbf{q}_j = d_j \mathbf{q}_j, \quad j = 1, \dots, n.$$

A has  $n$  real eigenvalues with  $n$  orthonormal eigenvectors.

# Diagonalization of Symmetric Matrices: Main Theorem

**Thm:** A matrix  $A \in \mathbb{R}^n$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^n$  and an orthogonal matrix  $Q$  so that

$$A = Q D Q^T = Q \begin{pmatrix} & & & \\ & & & \\ & & \diagdown & \\ & & & \diagup \\ & & & & \end{pmatrix} Q^T.$$

**Note:** Assume  $A = Q D Q^T$  with  $Q = (\mathbf{q}_1, \dots, \mathbf{q}_n)$  orthogonal, and  $D = \mathbf{diag}(d_1, \dots, d_n)$  diagonal. Then  $A Q = Q D$ ,

$$A (\mathbf{q}_1, \dots, \mathbf{q}_n) = (\mathbf{q}_1, \dots, \mathbf{q}_n) \mathbf{diag}(d_1, \dots, d_n) = (d_1 \mathbf{q}_1, \dots, d_n \mathbf{q}_n).$$

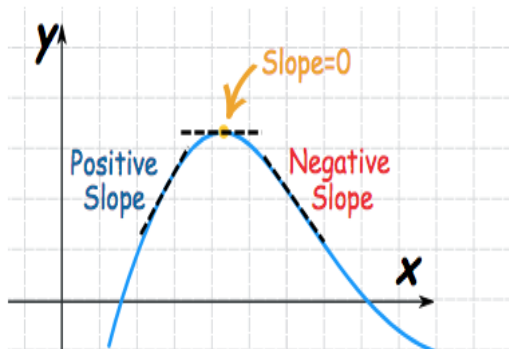
► Therefore

$$A \mathbf{q}_j = d_j \mathbf{q}_j, \quad j = 1, \dots, n.$$

A has  $n$  real eigenvalues with  $n$  orthonormal eigenvectors.

Will prove theorem with Calculus+material from §7.1-7.3 in MIXED order.

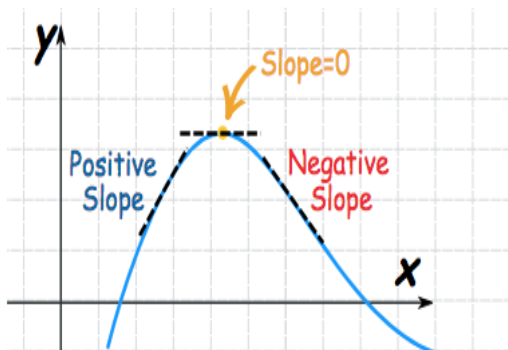
# Single Variable Calculus: Find MAXIMUM of function (I)



- ▶ Before MAXIMUM, function gets bigger with positive slope.
- ▶ After MAXIMUM, function gets smaller with negative slope.
- ▶ At MAXIMUM, function has 0 slope:  $f'(x) = 0$ .



## Single Variable Calculus: Find MAXIMUM of function (II)



**Thm** Let  $f(x) \in C[a, b]$  be continuously differentiable, then there exists  $x^* \in [a, b]$  so that

$$M = \max_{x \in [a, b]} f(x) = f(x^*).$$

- ▶ If  $x^* \neq a$  and  $x^* \neq b$ , then  $f'(x^*) = 0$ .

# Single Variable Calculus: Find MAXIMUM of function (III)

Example: A ball is thrown in the air. Its height at any time  $t$  is given by:

$$h = 3 + 14t - 5t^2$$

What is its maximum height?

Using [derivatives](#) we can find the slope of that function:

$$\begin{aligned}\frac{d}{dt} h &= 0 + 14 - 5(2t) \\ &= 14 - 10t\end{aligned}$$

(See below this example for how we found that derivative.)

Now find when the **slope is zero**:

$$\rightarrow 14 - 10t = 0$$

$$\rightarrow 10t = 14$$

$$\rightarrow t = 14 / 10 = \mathbf{1.4}$$

The slope is zero at  **$t = 1.4$  seconds**

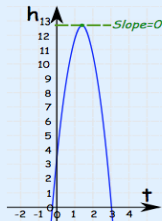
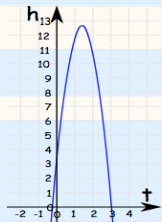
And the height at that time is:

$$\rightarrow h = 3 + 14 \times 1.4 - 5 \times 1.4^2$$

$$\rightarrow h = 3 + 19.6 - 9.8 = \mathbf{12.8}$$

And so:

The maximum height is **12.8 m** (at  $t = 1.4$  s)



# Multi-Variable Calculus: Gradient

- ▶ Multi-Variable function  $f(\mathbf{x}) \in \mathcal{R}$  for  $\mathbf{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathcal{R}^n$ .
- ▶ Gradient of  $f(\mathbf{x})$  is

$$\nabla f(\mathbf{x}) = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}.$$

- ▶ At MAXIMUM, function has **0** slope:  $\nabla f(\mathbf{x}) = \mathbf{0}$ .

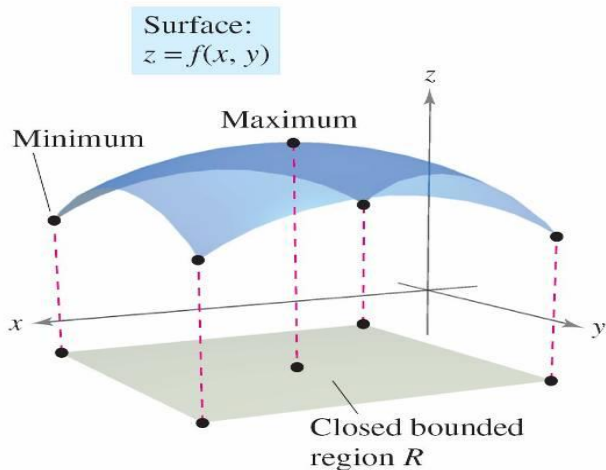
# Multi-Variable Calculus: Find MAXIMUM of function (I)

**Thm** Let function  $f(\mathbf{x}) \in \mathcal{R}$  be continuously differentiable for  $\mathbf{x}$  in closed region  $R \subset \mathcal{R}^n$ . Then there exists  $\mathbf{x}^* \in R$  so that

$$M = \max_{\mathbf{x} \in R} f(\mathbf{x}) = f(\mathbf{x}^*).$$

- ▶ If  $\mathbf{x}^*$  is not on boundary of  $R$ , then  $\nabla f(\mathbf{x}^*) = 0$ .

## Multi-Variable Calculus: Find MAXIMUM of function (II)



$R$  contains point(s) at which  $f(x, y)$  is a minimum and point(s) at which  $f(x, y)$  is a maximum.

## Multi-Variable Calculus: Find MAXIMUM of function (III)

For a symmetric matrix  $A \in \mathcal{R}^{n \times n}$ , define closed region

$$R = \{\mathbf{x} \in \mathcal{R}^n \mid \|\mathbf{x}\| = 1\}$$

and continuously differentiable function  $f(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$ .

There must exist  $\mathbf{x}^* \in R$  so that

$$M = \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x} = (\mathbf{x}^*)^T A (\mathbf{x}^*).$$

$$\text{Since } M = \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x} = \max_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}}.$$

$$\text{There exists } \mathbf{x}^* \neq \mathbf{0} \text{ so } M = \frac{(\mathbf{x}^*)^T A (\mathbf{x}^*)}{(\mathbf{x}^*)^T (\mathbf{x}^*)}.$$

## Multi-Variable Calculus: Find MAXIMUM of function (III)

For a symmetric matrix  $A \in \mathcal{R}^{n \times n}$ , define closed region

$$R = \{\mathbf{x} \in \mathcal{R}^n \mid \|\mathbf{x}\| = 1\}$$

and continuously differentiable function  $f(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$ .

There must exist  $\mathbf{x}^* \in R$  so that

$$M = \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x} = (\mathbf{x}^*)^T A (\mathbf{x}^*).$$

Since  $M = \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x} = \max_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$ .

There exists  $\mathbf{x}^* \neq \mathbf{0}$  so  $M = \frac{(\mathbf{x}^*)^T A (\mathbf{x}^*)}{(\mathbf{x}^*)^T (\mathbf{x}^*)}$ .

Equation  $\nabla \left( \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \right) = \mathbf{0}$  has solution.

# Gradient Calculus, with Chain rule (I)

By chain rule,

$$\nabla \left( \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \right) = \frac{\nabla (\mathbf{x}^T A \mathbf{x})}{\mathbf{x}^T \mathbf{x}} - \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \frac{\nabla (\mathbf{x}^T \mathbf{x})}{\mathbf{x}^T \mathbf{x}}.$$

With  $\mathbf{x}^T \mathbf{x} = x_1^2 + \cdots + x_n^2$ ,

$$\nabla (\mathbf{x}^T \mathbf{x}) = \begin{pmatrix} \frac{\partial(x_1^2 + \cdots + x_n^2)}{\partial x_1} \\ \vdots \\ \frac{\partial(x_1^2 + \cdots + x_n^2)}{\partial x_n} \end{pmatrix} = 2 \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = 2 \mathbf{x}.$$



## Gradient Calculus, with Chain rule (II)

$$\begin{aligned}\text{With } \mathbf{x}^T A \mathbf{x} = & x_1 (a_{11} x_1 + a_{12} x_2 + \cdots + a_{1n} x_n) \\ & + x_2 (a_{21} x_1 + a_{22} x_2 + \cdots + a_{2n} x_n) + \cdots \\ & + x_n (a_{n1} x_1 + a_{n2} x_2 + \cdots + a_{nn} x_n)\end{aligned}$$

$$\begin{aligned}\frac{\partial (\mathbf{x}^T A \mathbf{x})}{\partial x_1} &= (a_{11} x_1 + a_{12} x_2 + \cdots + a_{1n} x_n) + x_1 a_{11} + x_2 a_{21} + \cdots + x_n a_{n1} \\ &= 2 (a_{11} x_1 + a_{12} x_2 + \cdots + a_{1n} x_n) = 2 (A \mathbf{x})_1,\end{aligned}$$

$$\frac{\partial (\mathbf{x}^T A \mathbf{x})}{\partial x_j} = 2 (a_{j1} x_1 + a_{j2} x_2 + \cdots + a_{jn} x_n) = 2 (A \mathbf{x})_j, \quad j = 1, \dots, n.$$

$$\text{With } \nabla (\mathbf{x}^T A \mathbf{x}) = \begin{pmatrix} \frac{\partial (\mathbf{x}^T A \mathbf{x})}{\partial x_1} \\ \vdots \\ \frac{\partial (\mathbf{x}^T A \mathbf{x})}{\partial x_n} \end{pmatrix} = 2 A \mathbf{x}.$$

## Multi-Variable Calculus: Find MAXIMUM of function (IV)

By chain rule,

$$\nabla \left( \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \right) = \frac{\nabla (\mathbf{x}^T A \mathbf{x})}{\mathbf{x}^T \mathbf{x}} - \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \frac{\nabla (\mathbf{x}^T \mathbf{x})}{\mathbf{x}^T \mathbf{x}}.$$

But

$$\nabla (\mathbf{x}^T \mathbf{x}) = 2\mathbf{x}, \quad \nabla (\mathbf{x}^T A \mathbf{x}) = 2A\mathbf{x}.$$

Therefore there is solution to

$$\nabla \left( \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \right) = \frac{2A\mathbf{x}}{\mathbf{x}^T \mathbf{x}} - \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \frac{2\mathbf{x}}{\mathbf{x}^T \mathbf{x}} = \mathbf{0},$$

or  $A\mathbf{x} = \lambda\mathbf{x}$ , for  $\mathbf{x} \neq \mathbf{0}$ . (with eigenvalue  $\lambda = \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$ .)

Therefore  $M = \max_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$  must be an eigenvalue.

# Eigenvector-induced Orthonormal Basis

Let  $\lambda$  be eigenvalue of  $A$  with eigenvector  $\mathbf{v}$ :  $A\mathbf{v} = \lambda\mathbf{v}$ .

- ▶ We extend  $\mathbf{v}$  into a basis for  $\mathbb{R}^n$ :  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  with  $\mathbf{v}_1 = \mathbf{v}$ .
- ▶ Use Gram-Schmidt to obtain an orthogonal basis for  $\mathbb{R}^n$ :  $\hat{\mathbf{v}}_1, \hat{\mathbf{v}}_2, \dots, \hat{\mathbf{v}}_n$  with  $\hat{\mathbf{v}}_1 = \mathbf{v}$ .
- ▶ Define orthogonal matrix  $U \in \mathbb{R}^{n \times n}$

$$U \stackrel{\text{def}}{=} \left( \frac{\hat{\mathbf{v}}_1}{\|\hat{\mathbf{v}}_1\|}, \dots, \frac{\hat{\mathbf{v}}_n}{\|\hat{\mathbf{v}}_n\|} \right) \stackrel{\text{def}}{=} (\mathbf{u}_1, \dots, \mathbf{u}_n)$$

- ▶  $\lambda$  is eigenvalue of  $A$  with UNIT eigenvector  $\mathbf{u}_1$ :  $A\mathbf{u}_1 = \lambda\mathbf{u}_1$ ;  
columns of  $U$  orthonormal basis for  $\mathbb{R}^n$ .

## Eigenvector-induced Orthonormal Basis: EXAMPLE

Matrix  $A = \begin{pmatrix} 3 & 2 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 4 \end{pmatrix} \in \mathcal{R}^{3 \times 3}$  is symmetric with

eigenvalue  $\lambda = 6$  and eigenvector  $\mathbf{v} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ .

- ▶ An orthogonal basis for  $\mathbb{R}^3$ :

$$\hat{\mathbf{v}}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \hat{\mathbf{v}}_2 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \quad \hat{\mathbf{v}}_3 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}.$$

- ▶ Define orthogonal matrix  $U \in \mathbb{R}^{n \times n}$

$$U \stackrel{\text{def}}{=} \begin{pmatrix} \hat{\mathbf{v}}_1 & \hat{\mathbf{v}}_2 & \hat{\mathbf{v}}_3 \\ \hline \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \end{pmatrix}$$

- ▶  $\lambda$  is eigenvalue of  $A$  with UNIT eigenvector

$$\frac{\hat{\mathbf{v}}_1}{\sqrt{3}} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

**Thm:** A matrix  $A \in \mathbb{R}^n$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^n$  and an orthogonal matrix  $Q$  so that

$$A = Q D Q^T = Q \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{pmatrix} Q^T.$$

**Thm:** A matrix  $A \in \mathbb{R}^n$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^n$  and an orthogonal matrix  $Q$  so that

$$A = Q D Q^T = Q \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{pmatrix} Q^T.$$

**Proof:**

- ▶ By induction on  $n$ . Assume theorem true for  $n - 1$ .
- ▶ Let  $\lambda$  be eigenvalue of  $A$  with UNIT eigenvector  $\mathbf{u}$ :  $A\mathbf{u} = \lambda\mathbf{u}$ .
- ▶ We extend  $\mathbf{u}$  into an orthonormal basis for  $\mathbb{R}^n$ :  $\mathbf{u}, \mathbf{u}_2, \dots, \mathbf{u}_n$  are unit, mutually orthogonal vectors.

- ▶  $U \stackrel{\text{def}}{=} (\mathbf{u}, \mathbf{u}_2, \dots, \mathbf{u}_n) \stackrel{\text{def}}{=} (\mathbf{u}, \hat{U}) \in \mathbb{R}^{n \times n}$  is orthogonal.

$$\begin{aligned} U^T A U &= \begin{pmatrix} \mathbf{u}^T \\ \hat{U}^T \end{pmatrix} (A\mathbf{u}, A\hat{U}) = \begin{pmatrix} \mathbf{u}^T (A\mathbf{u}) & \mathbf{u}^T (A\hat{U}) \\ \hat{U}^T (A\mathbf{u}) & \hat{U}^T (A\hat{U}) \end{pmatrix} \\ &= \begin{pmatrix} \lambda & \mathbf{0}^T \\ \mathbf{0} & \hat{U}^T (A\hat{U}) \end{pmatrix}. \end{aligned}$$

- ▶ Matrix  $\hat{U}^T (A\hat{U}) \in \mathbb{R}^{(n-1) \times (n-1)}$  is symmetric.

**Thm:** A matrix  $A \in \mathbb{R}^{n \times n}$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^{n \times n}$  and an orthogonal matrix  $Q$  so

$$\text{that } A = Q D Q^T = Q \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{pmatrix} Q^T.$$

**Thm:** A matrix  $A \in \mathbb{R}^{n \times n}$  is symmetric if and only if there exists a diagonal matrix  $D \in \mathbb{R}^{n \times n}$  and an orthogonal matrix  $Q$  so

$$\text{that } A = Q D Q^T = Q \begin{pmatrix} & & & \\ & & & \\ & & \diagdown & \\ & & & \end{pmatrix} Q^T.$$

**Proof:** ▶

$$U^T A U = \begin{pmatrix} \lambda & \mathbf{0}^T \\ \mathbf{0} & \hat{U}^T (A \hat{U}) \end{pmatrix}.$$

▶ By induction, there exist diagonal matrix  $\hat{D}$  and orthogonal matrix  $\hat{Q} \in \mathbb{R}^{(n-1) \times (n-1)}$ ,

$$\hat{U}^T (A \hat{U}) = \hat{Q} \hat{D} \hat{Q}^T.$$

▶ therefore

$$U^T A U = \begin{pmatrix} \lambda & \mathbf{0}^T \\ \mathbf{0} & \hat{Q} \hat{D} \hat{Q}^T \end{pmatrix}.$$

$$A = \left( U \begin{pmatrix} 1 & \\ & \hat{Q} \end{pmatrix} \right) \begin{pmatrix} \lambda & \\ & \hat{D} \end{pmatrix} \left( U \begin{pmatrix} 1 & \\ & \hat{Q} \end{pmatrix} \right)^T \stackrel{\text{def}}{=} Q D Q^T.$$



**Thm:** Let matrix  $A \in \mathbb{R}^{n \times n}$  be symmetric, then

$M \stackrel{\text{def}}{=} \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x}$  is the greatest eigenvalue of  $A$ ,

$m \stackrel{\text{def}}{=} \min_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x}$  is the least eigenvalue of  $A$ .

**Proof:** Write  $A = Q D Q^T$ , with orthogonal matrix  $Q \in \mathbb{R}^{n \times n}$  and diagonal matrix  $D = \mathbf{diag}(\lambda_1, \dots, \lambda_n)$  with eigenvalues.

**Thm:** Let matrix  $A \in \mathbb{R}^{n \times n}$  be symmetric, then

$M \stackrel{\text{def}}{=} \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x}$  is the greatest eigenvalue of  $A$ ,

$m \stackrel{\text{def}}{=} \min_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x}$  is the least eigenvalue of  $A$ .

**Proof:** Write  $A = Q D Q^T$ , with orthogonal matrix  $Q \in \mathbb{R}^{n \times n}$  and diagonal matrix  $D = \mathbf{diag}(\lambda_1, \dots, \lambda_n)$  with eigenvalues.

► Define change of variable  $\mathbf{y} = Q^T \mathbf{x}$ . Then  $\|\mathbf{y}\| = \|\mathbf{x}\|$  for all  $\mathbf{x}$ ,

$$\text{and } M = \max_{\|\mathbf{y}\|=1} \mathbf{y}^T D \mathbf{y}, \quad m = \min_{\|\mathbf{y}\|=1} \mathbf{y}^T D \mathbf{y}.$$

**Proof:** Write  $A = Q D Q^T$ ,  $D = \mathbf{diag}(\lambda_1, \dots, \lambda_n)$  with eigenvalues,

and  $M = \max_{\|\mathbf{y}\|=1} \mathbf{y}^T D \mathbf{y}$ ,  $m = \min_{\|\mathbf{y}\|=1} \mathbf{y}^T D \mathbf{y}$ , for  $\mathbf{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$ .

$$\mathbf{y}^T D \mathbf{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}^T \mathbf{diag}(\lambda_1, \dots, \lambda_n) \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2.$$

Let  $\lambda_{\mathbf{max}} = \max\{\lambda_1, \dots, \lambda_n\} = \lambda_{\ell_1}$ ,  $\lambda_{\mathbf{min}} = \min\{\lambda_1, \dots, \lambda_n\} = \lambda_{\ell_2}$ , then

$$\lambda_{\mathbf{min}} (y_1^2 + \dots + y_n^2) \leq \lambda_1 y_1^2 + \dots + \lambda_n y_n^2 \leq \lambda_{\mathbf{max}} (y_1^2 + \dots + y_n^2).$$

$$\text{or, } \lambda_{\mathbf{min}} \|\mathbf{y}\|^2 \leq \mathbf{y}^T D \mathbf{y} \leq \lambda_{\mathbf{max}} \|\mathbf{y}\|^2.$$

So for all  $\|\mathbf{y}\| = 1$ ,  $\lambda_{\mathbf{min}} \leq m \leq \mathbf{y}^T D \mathbf{y} \leq M \leq \lambda_{\mathbf{max}}$ .

**Proof:** For  $D = \mathbf{diag}(\lambda_1, \dots, \lambda_n)$  with eigenvalues,

$$M = \max_{\|\mathbf{y}\|=1} \mathbf{y}^T D \mathbf{y}, \quad m = \min_{\|\mathbf{y}\|=1} \mathbf{y}^T D \mathbf{y}, \quad \text{for } \mathbf{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}.$$
$$\mathbf{y}^T D \mathbf{y} = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2.$$

Let  $\lambda_{\mathbf{max}} = \max\{\lambda_1, \dots, \lambda_n\} = \lambda_{\ell_1}$ ,  $\lambda_{\mathbf{min}} = \min\{\lambda_1, \dots, \lambda_n\} = \lambda_{\ell_2}$ , then

$$\text{for all } \|\mathbf{y}\| = 1, \quad \lambda_{\mathbf{min}} \leq m \leq \mathbf{y}^T D \mathbf{y} \leq M \leq \lambda_{\mathbf{max}}.$$

- ▶ Let  $\mathbf{e}_j$  be the  $j^{\text{th}}$  column of the identity.
  - ▶ Choose  $\mathbf{y} = \mathbf{e}_{\ell_1}$ , then  $M \geq \mathbf{y}^T D \mathbf{y} = \lambda_{\mathbf{max}}$ .
  - ▶ Choose  $\mathbf{y} = \mathbf{e}_{\ell_2}$ , then  $m \leq \mathbf{y}^T D \mathbf{y} = \lambda_{\mathbf{min}}$ .
- ▶ Therefore  $M = \lambda_{\mathbf{max}}$ ,  $m = \lambda_{\mathbf{min}}$ .

**Thm:** Let matrix  $A \in \mathbb{R}^{n \times n}$  be symmetric, then

$M \stackrel{\text{def}}{=} \max_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x}$  is the greatest eigenvalue of  $A$ ,

$m \stackrel{\text{def}}{=} \min_{\|\mathbf{x}\|=1} \mathbf{x}^T A \mathbf{x}$  is the least eigenvalue of  $A$ .

EXAMPLE: Matrix  $A = \begin{pmatrix} 3 & 2 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 4 \end{pmatrix} \in \mathcal{R}^{3 \times 3}$  is symmetric with eigenvalues  $\lambda_1 = 6$ ,  $\lambda_2 = 3$ ,  $\lambda_3 = 1$  and unit eigenvectors

$$\mathbf{u}_1 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \mathbf{u}_2 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, \quad \mathbf{u}_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}.$$

Therefore

$$M = \mathbf{u}_1^T A \mathbf{u}_1 = 6, \quad m = \mathbf{u}_3^T A \mathbf{u}_3 = 1.$$