

## §5.4 Eigenvectors and Linear Transformations

- ▶ Let  $V, W = n$ -dimensional and  $m$ -dimensional Vector Spaces.
- ▶ Let  $T$  = linear transformation from  $V$  to  $W$ .
- ▶ Let  $\mathcal{B}$  and  $\mathcal{C}$  be bases for  $V, W$ .

Given  $\mathbf{x} \in V$ ,  $[T(\mathbf{x})]_{\mathcal{C}} = (?) [\mathbf{x}]_{\mathcal{B}}$

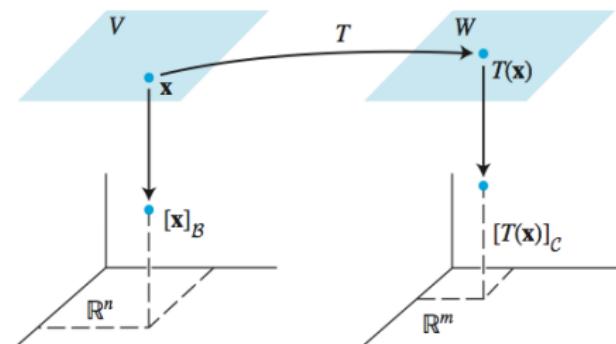


FIGURE 1 A linear transformation from  $V$  to  $W$ .

## Matrix for $T$ relative to $\mathcal{B}$ and $\mathcal{C}$

Let  $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \cdots + \alpha_n \mathbf{b}_n$  so that  $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$ .

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$$\begin{aligned} T(\mathbf{x}) &= \alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n), \\ [T(\mathbf{x})]_{\mathcal{C}} &= [\alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n)]_{\mathcal{C}} \end{aligned}$$

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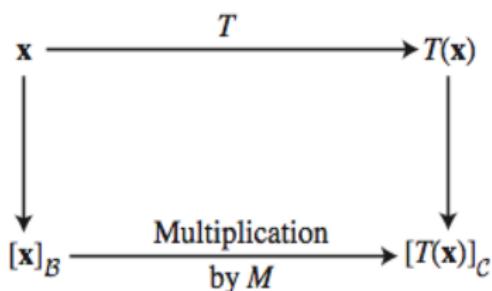
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$$\begin{aligned} T(\mathbf{x}) &= \alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n), \\ [T(\mathbf{x})]_{\mathcal{C}} &= [\alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n)]_{\mathcal{C}} = \alpha_1 [T(\mathbf{b}_1)]_{\mathcal{C}} + \cdots + \alpha_n [T(\mathbf{b}_n)]_{\mathcal{C}} \\ &= [[T(\mathbf{b}_1)]_{\mathcal{C}}, [T(\mathbf{b}_2)]_{\mathcal{C}}, \dots, [T(\mathbf{b}_n)]_{\mathcal{C}}] \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} \stackrel{\text{def}}{=} M [\mathbf{x}]_{\mathcal{B}} \end{aligned}$$



**EX:** Consider bases:  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$  for  $V$ ,  $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \mathbf{c}_3\}$  for  $W$ .  
 $T : V \rightarrow W$  is linear transformation satisfying

$$T(\mathbf{b}_1) = 3\mathbf{c}_1 - 2\mathbf{c}_2 + 5\mathbf{c}_3 \quad \text{and} \quad T(\mathbf{b}_2) = 4\mathbf{c}_1 + 7\mathbf{c}_2 - \mathbf{c}_3.$$

Find  $M$ , Matrix for  $T$  relative to  $\mathcal{B}$  and  $\mathcal{C}$ .

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Find  $M$ , Matrix for  $T$  relative to  $\mathcal{B}$  and  $\mathcal{C}$ .

**SOLUTION:** By definition,

$$[T(\mathbf{b}_1)]_{\mathcal{C}} = \begin{bmatrix} 3 \\ -2 \\ 5 \end{bmatrix}, \quad \text{and} \quad [T(\mathbf{b}_2)]_{\mathcal{C}} = \begin{bmatrix} 4 \\ 7 \\ -1 \end{bmatrix}.$$

$$\text{Hence } M = \begin{bmatrix} 3 & 4 \\ -2 & 7 \\ 5 & -1 \end{bmatrix}.$$

## Matrix relative to $\mathcal{B}$ for $T : V \rightarrow V$ .

Let  $x = \alpha_1 \mathbf{b}_1 + \cdots + \alpha_n \mathbf{b}_n$  so that  $[x]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$ .

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$$\begin{aligned} T(x) &= \alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n), \\ [T(x)]_{\mathcal{B}} &= [\alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n)]_{\mathcal{B}} \end{aligned}$$

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$$[T(x)]_{\mathcal{B}} = [\alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n)]_{\mathcal{B}} = \alpha_1 [T(\mathbf{b}_1)]_{\mathcal{B}} + \cdots + \alpha_n [T(\mathbf{b}_n)]_{\mathcal{B}}$$

## Matrix relative to $\mathcal{B}$ for $T : V \rightarrow V$ .

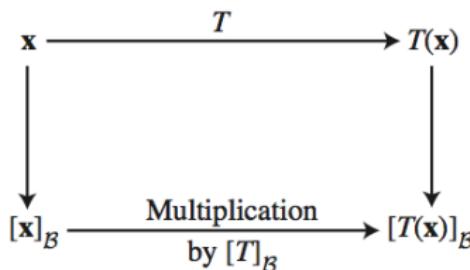
Let  $x = \alpha_1 \mathbf{b}_1 + \cdots + \alpha_n \mathbf{b}_n$  so that  $[x]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$ .

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Let  $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \cdots + \alpha_n \mathbf{b}_n$  so that  $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$ .

$$\begin{aligned} T(\mathbf{x}) &= \alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n), \\ [T(\mathbf{x})]_{\mathcal{B}} &= [\alpha_1 T(\mathbf{b}_1) + \cdots + \alpha_n T(\mathbf{b}_n)]_{\mathcal{B}} = \alpha_1 [T(\mathbf{b}_1)]_{\mathcal{B}} + \cdots + \alpha_n [T(\mathbf{b}_n)]_{\mathcal{B}} \\ &= [[T(\mathbf{b}_1)]_{\mathcal{B}}, [T(\mathbf{b}_2)]_{\mathcal{B}}, \dots, [T(\mathbf{b}_n)]_{\mathcal{B}}] \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} \stackrel{\text{def}}{=} [T]_{\mathcal{B}} [\mathbf{x}]_{\mathcal{B}} \end{aligned}$$



**EX:** Consider linear transformation:  $T : \mathcal{P}_2 \rightarrow \mathcal{P}_2$  defined by

$$T(a_0 + a_1 t + a_2 t^2) = a_1 + 2a_2 t.$$

- a. Find  $[T]_{\mathcal{B}}$  for basis  $\mathcal{B} = \{1, t, t^2\}$ .
- b. Verify  $[T(\mathbf{p})]_{\mathcal{B}} = [T]_{\mathcal{B}} [\mathbf{p}]_{\mathcal{B}}$  for each  $\mathbf{p} \in \mathcal{P}_2$ .

SOLUTION (a):  $T(1) = 0$ ,  $T(t) = 1$ ,  $T(t^2) = 2t$ . Hence

$$[T(1)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, [T(t)]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, [T(t^2)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}.$$

$$[T]_{\mathcal{B}} = [[T(1)]_{\mathcal{B}}, [T(t)]_{\mathcal{B}}, [T(t^2)]_{\mathcal{B}}] = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

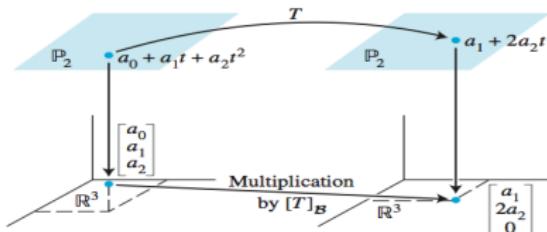
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**b.** Verify  $[T(\mathbf{p})]_{\mathcal{B}} = [T]_{\mathcal{B}} [\mathbf{p}]_{\mathcal{B}}$  for each  $\mathbf{p} \in \mathcal{P}_2$ .

SOLUTION (b): For  $\mathbf{p}(t) = a_0 + a_1 t + a_2 t^2$ ,  $T(\mathbf{p})(t) = a_1 + 2a_2 t$ .

$$[\mathbf{p}]_{\mathcal{B}} = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix}, \quad [T(\mathbf{p})]_{\mathcal{B}} = \begin{bmatrix} a_1 \\ 2a_2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = [T]_{\mathcal{B}} [\mathbf{p}]_{\mathcal{B}}.$$



**FIGURE 4** Matrix representation of a linear transformation.

## Linear Transformation on $\mathcal{R}^n$

- ▶ For  $A \in \mathcal{R}^{n \times n}$ , define linear transformation on  $\mathcal{R}^n$ :  
 $T(\mathbf{x}) = A\mathbf{x}$ .

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Find  $[T]_{\mathcal{B}} = [[T(\mathbf{b}_1)]_{\mathcal{B}}, [T(\mathbf{b}_2)]_{\mathcal{B}}, \dots, [T(\mathbf{b}_n)]_{\mathcal{B}}]$ ?

By definition,  $T(\mathbf{b}_1) = A\mathbf{b}_1$ . Let  $[T(\mathbf{b}_1)]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$  so that

$$A\mathbf{b}_1 = \alpha_1 \mathbf{b}_1 + \alpha_2 \mathbf{b}_2 + \cdots + \alpha_n \mathbf{b}_n = [\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n] \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix},$$

$$\implies [T(\mathbf{b}_1)]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} = P^{-1}(A\mathbf{b}_1), \quad \text{with} \quad P = [\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n].$$

## Linear Transformation on $\mathcal{R}^n$

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$$\begin{aligned}[T]_{\mathcal{B}} &= [[T(\mathbf{b}_1)]_{\mathcal{B}}, [T(\mathbf{b}_2)]_{\mathcal{B}}, \dots, [T(\mathbf{b}_n)]_{\mathcal{B}}] \\ &= [P^{-1}(A\mathbf{b}_1), P^{-1}(A\mathbf{b}_2), \dots, P^{-1}(A\mathbf{b}_n)] \\ &= P^{-1}A[\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n] = P^{-1}AP\end{aligned}$$

Goal: Choose  $\mathcal{B}$  to make  $[T]_{\mathcal{B}}$  as simple as possible.

$$\text{For any } \mathbf{x} \in \mathcal{R}^n, \quad [A\mathbf{x}]_{\mathcal{B}} = [T(\mathbf{x})]_{\mathcal{B}} = [T]_{\mathcal{B}} [\mathbf{x}]_{\mathcal{B}}.$$

## Linear Transformation on $\mathbb{R}^2$ : EX 1

- For  $A = \begin{bmatrix} 7 & 2 \\ -4 & 1 \end{bmatrix}$ , define linear transformation on  $\mathbb{R}^2$ :  
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SOLUTION: From example in §5.3,

$$A = P D P^{-1}, \quad \text{where} \quad P = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}, \quad D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}.$$

Choose  $\mathbf{b}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$  to be columns of  $P$ . Then

$$[T]_{\mathcal{B}} = P^{-1} A P = D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}, \quad (\text{diagonal matrix})$$

## Linear Transformation on $\mathbb{R}^2$ : EX 2

- ▶ For  $A = \begin{bmatrix} 4 & -9 \\ 4 & -8 \end{bmatrix}$ , define linear transformation on  $\mathbb{R}^2$ :  
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- ▶ SOLUTION: Find eigenvalues of  $A$

$$\det(A - \lambda I) = \det \begin{pmatrix} 4 - \lambda & -9 \\ 4 & -8 - \lambda \end{pmatrix} = (2 + \lambda)^2.$$

So eigenvalues are  $\lambda_1 = \lambda_2 = -2$ .

- ▶ Find eigenvectors of  $A$

$$(A - \lambda_1 I)\mathbf{v} = \begin{pmatrix} 6 & -9 \\ 4 & -6 \end{pmatrix}\mathbf{v} = \mathbf{0}, \quad \Rightarrow \quad \mathbf{v}_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}.$$

- ▶ Choose  $\mathbf{v}_2 = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $P = [\mathbf{v}_1, \mathbf{v}_2]$  and  $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2\}$ .

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- SOLUTION: Eigenvalues  $\lambda_1 = \lambda_2 = -2$ . Only eigenvector  $\mathbf{v}_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ .
- Choose  $\mathbf{v}_2 = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $P = [\mathbf{v}_1, \mathbf{v}_2]$  and  $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2\}$ .

$$A\mathbf{v}_1 = -2\mathbf{v}_1, \quad A\mathbf{v}_2 = \begin{bmatrix} 4 & -9 \\ 4 & -8 \end{bmatrix} \begin{bmatrix} -2 \\ 3 \end{bmatrix} = \begin{bmatrix} -35 \\ -32 \end{bmatrix} = -13\mathbf{v}_1 - 2\mathbf{v}_2$$

$$AP = A[\mathbf{v}_1 \ \mathbf{v}_2] = [-2\mathbf{v}_1, -13\mathbf{v}_1 - 2\mathbf{v}_2] = [\mathbf{v}_1 \ \mathbf{v}_2] \begin{bmatrix} -2 & -13 \\ 0 & -2 \end{bmatrix}$$

Then  $[T]_{\mathcal{B}} = P^{-1}AP = \begin{bmatrix} -2 & -13 \\ 0 & -2 \end{bmatrix}$ , (upper triangular matrix)

## §6.1 Inner Product

Let  $\mathbf{u} = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \in \mathcal{R}^n$ .

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- ▶ **length** of  $\mathbf{u}$  (denoted  $\|\mathbf{u}\|$ )  $\stackrel{\text{def}}{=} \sqrt{u_1^2 + \cdots + u_n^2} = \sqrt{\mathbf{u}^T \mathbf{u}}$

**EX:** Let  $\mathbf{u} = \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \in \mathbb{R}^3$ .

- ▶ **inner product** of  $\mathbf{u}$  and  $\mathbf{v} = 3 \cdot 1 + (-5) \cdot 2 + 2 \cdot 1 = -5$

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- ▶ **inner product** of  $\mathbf{u}$  and  $\mathbf{v} = 3 \cdot 1 + (-5) \cdot 2 + 2 \cdot 1 = -5$
- ▶ **length** of  $\mathbf{u}$  :  $\|\mathbf{u}\| = \sqrt{3^2 + (-5)^2 + 2^2} = \sqrt{38}$

Let  $\mathbf{u} = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \in \mathcal{R}^n$ .

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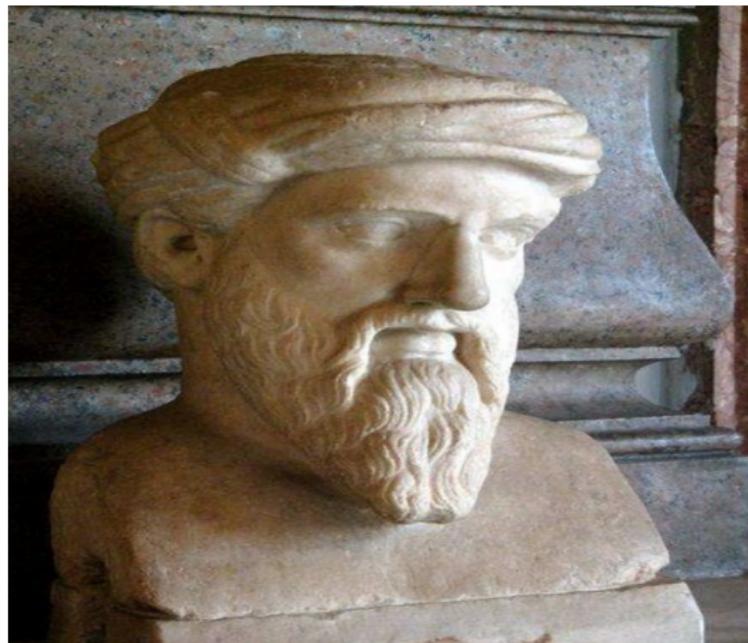
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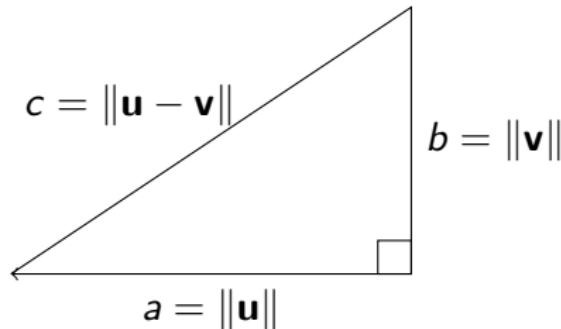
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**Pythagorean Thm:**  $\|\mathbf{u} - \mathbf{v}\|^2 = (41 = 38 + 3 =) \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$

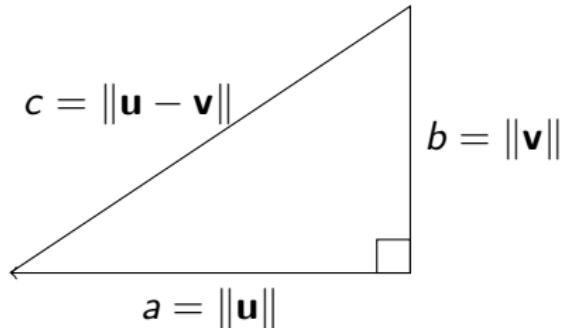
# Pythagoras



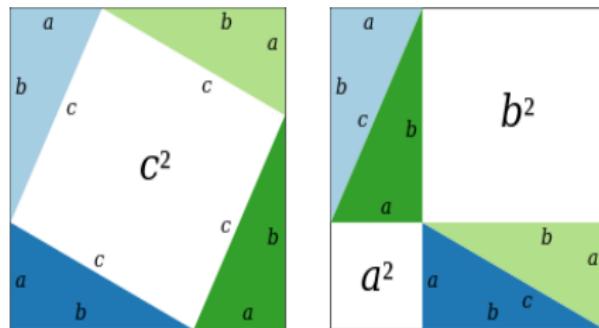
## ► Pythagorean Thm



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## ► Pythagorean PROOF



$$c^2 = a^2 + b^2$$

## Orthogonal Complement of subspace $W$ of $\mathbb{R}^m$

- ▶ **orthogonal complement** of  $W$  (denoted  $W^\perp$ )

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- $W^\perp = \text{Nul } A^T$ , where  $A^T \stackrel{\text{def}}{=} [\mathbf{a}_1, \mathbf{a}_2]^T = \begin{bmatrix} 1 & 2 & 1 \\ 3 & -2 & 1 \end{bmatrix}$ .
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$$\alpha_1 \mathbf{u}_1 + \alpha_2 \mathbf{u}_2 + \cdots + \alpha_p \mathbf{u}_p = \mathbf{0}. \quad (\ell_1)$$

- ▶ Inner product with  $\mathbf{u}_j$  on both sides of  $(\ell_1)$ , for  $j = 1, \dots, p$

$$\mathbf{u}_j^T (\alpha_1 \mathbf{u}_1 + \alpha_2 \mathbf{u}_2 + \cdots + \alpha_p \mathbf{u}_p) = 0. \quad (\ell_2)$$

- ▶ All cross terms in  $(\ell_2)$  die due to orthogonality:

$$\alpha_j \mathbf{u}_j^T \mathbf{u}_j = 0. \implies \text{Must have } \alpha_j = 0 \text{ since } \mathbf{u}_j \neq \mathbf{0}.$$

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Express  $\mathbf{y} = \begin{bmatrix} 6 \\ 1 \\ -8 \end{bmatrix}$  as linear combination of vectors in  $\mathcal{S}$ .

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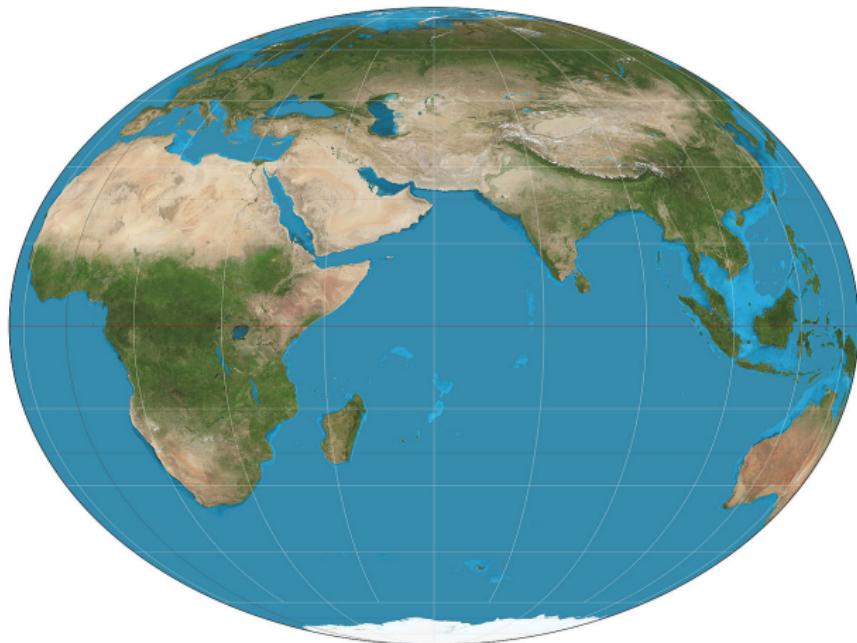
$$\alpha_1 = \frac{\mathbf{y}^T \mathbf{u}_1}{\mathbf{u}_1^T \mathbf{u}_1} = \frac{11}{11} = 1,$$

$$\alpha_2 = \frac{\mathbf{y}^T \mathbf{u}_2}{\mathbf{u}_2^T \mathbf{u}_2} = \frac{-12}{6} = -2,$$

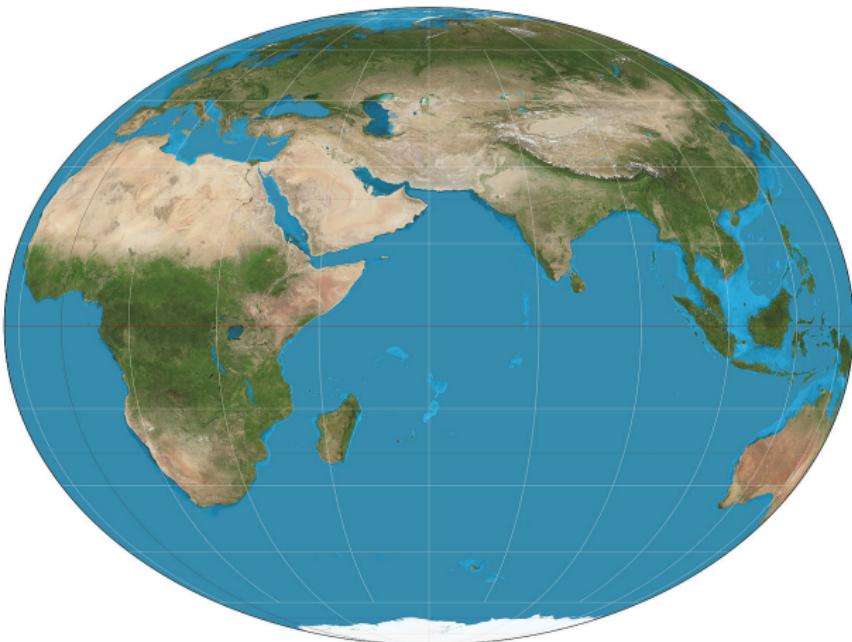
$$\alpha_3 = \frac{\mathbf{y}^T \mathbf{u}_3}{\mathbf{u}_3^T \mathbf{u}_3} = \frac{-66}{66} = -1.$$

- So  $\mathbf{y} = \mathbf{u}_1 - 2 \mathbf{u}_2 - \mathbf{u}_3$ .

Eastern hemisphere?



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**orthogonal projection:** Humans evolutionary trained to see 3D in 2D views

# Orthogonal Projection

- ▶ Given non-zero vector  $\mathbf{u} \in \mathbb{R}^n$ .
- ▶ For any vector  $\mathbf{y} \in \mathbb{R}^n$ , decompose

$$\mathbf{y} = \hat{\mathbf{y}} + \mathbf{z}, \quad \text{where } \hat{\mathbf{y}} \in \text{Span}\{\mathbf{u}\}, \quad \mathbf{z} \in (\text{Span}\{\mathbf{u}\})^\perp. \quad (\ell_1)$$

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- ▶ Let  $\hat{\mathbf{y}} = \alpha \mathbf{u}$ . Re-write  $(\ell_1)$  as

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- ▶ **orthogonal projection**

$$\boxed{\hat{\mathbf{y}} = \mathbf{Proj}_L \mathbf{y} \stackrel{\text{def}}{=} \frac{\mathbf{y}^T \mathbf{u}}{\mathbf{u}^T \mathbf{u}} \mathbf{u}},$$

$(L = \text{Span}\{\mathbf{u}\})$

## Orthonormal Set

- ▶ DEFINITION: Set  $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_p\}$  is **orthonormal set** if  $\mathcal{S}$  is orthogonal set of unit vectors.
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$$\mathbf{v}_1 = \frac{\mathbf{u}_1}{\|\mathbf{u}_1\|}, \quad \mathbf{v}_2 = \frac{\mathbf{u}_2}{\|\mathbf{u}_2\|}, \quad \mathbf{v}_3 = \frac{\mathbf{u}_3}{\|\mathbf{u}_3\|}.$$

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- ▶  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is orthonormal basis for  $\mathbb{R}^3$

**Thm:** Matrix  $U \in \mathbb{R}^{m \times n}$  has orthonormal columns  $\iff U^T U = I$ .

PROOF: Let  $U = (\mathbf{u}_1, \dots, \mathbf{u}_n)$ . Then

$$U^T U = \begin{pmatrix} \mathbf{u}_1^T \\ \vdots \\ \mathbf{u}_n^T \end{pmatrix} (\mathbf{u}_1, \dots, \mathbf{u}_n) = (\mathbf{u}_i^T \mathbf{u}_j).$$

The  $(i, j)$  entry of  $U^T U$  is  $\mathbf{u}_i^T \mathbf{u}_j$ .

- ▶ For  $i = j$ :  $\mathbf{u}_i^T \mathbf{u}_i = 1$ , each column of  $U$  has unit length.
- ▶ For  $i \neq j$ :  $\mathbf{u}_i^T \mathbf{u}_j = 0$ , each pair of columns of  $U$  is orthogonal.

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$$\mathbf{v}_1 = \frac{1}{\sqrt{11}} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \frac{1}{\sqrt{66}} \begin{bmatrix} -1 \\ -4 \\ 7 \end{bmatrix}.$$

$$U = \begin{bmatrix} \frac{3}{\sqrt{11}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{66}} \\ \frac{1}{\sqrt{11}} & \frac{2}{\sqrt{6}} & -\frac{4}{\sqrt{66}} \\ \frac{1}{\sqrt{11}} & \frac{1}{\sqrt{6}} & \frac{7}{\sqrt{66}} \end{bmatrix}.$$

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**Thm:** Let  $U \in \mathbb{R}^{m \times n}$  have orthonormal columns. Then for  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$

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$$U = \begin{bmatrix} \frac{3}{\sqrt{11}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{66}} \\ \frac{1}{\sqrt{11}} & \frac{2}{\sqrt{6}} & -\frac{4}{\sqrt{66}} \\ \frac{1}{\sqrt{11}} & \frac{1}{\sqrt{6}} & \frac{7}{\sqrt{66}} \\ \frac{1}{\sqrt{11}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{66}} \end{bmatrix}.$$

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- ▶  $U^T U = I, \quad U \in \mathbb{R}^{3 \times 3} \Rightarrow \quad U^{-1} = U^T.$
- ▶ DEFINITION: Square matrix of orthonormal columns is **orthogonal matrix**.

## §6.3 Orthogonal Projection

Let  $W$  be a subspace of  $\mathbb{R}^n$  with orthogonal basis  $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ .

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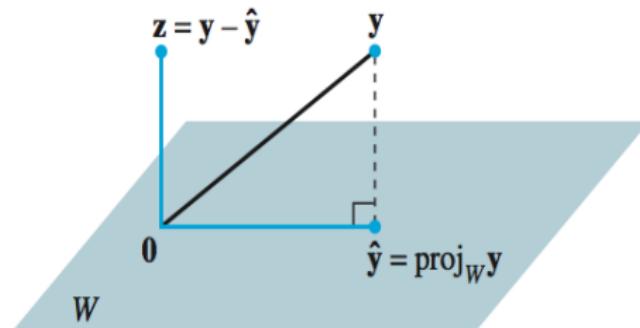
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**FIGURE 2** The orthogonal projection of  $\mathbf{y}$  onto  $W$ .

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## Orthogonal Projection, EXAMPLE

Let  $W \stackrel{\text{def}}{=} \text{Span} \{ \mathbf{v}_1, \mathbf{v}_2 \}$ , with  $\mathbf{v}_1 = \frac{1}{\sqrt{11}} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}$ ,  $\mathbf{v}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$

and  $\mathbf{y} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$ . Write  $\mathbf{y} = \hat{\mathbf{y}} + \mathbf{z}$ , with  $\hat{\mathbf{y}} \in W$ ,  $\mathbf{z} \in W^\perp$ ,

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SOLUTION:

$$\hat{\mathbf{y}} = \frac{\mathbf{y}^T \mathbf{v}_1}{\mathbf{v}_1^T \mathbf{v}_1} \mathbf{v}_1 + \frac{\mathbf{y}^T \mathbf{v}_2}{\mathbf{v}_2^T \mathbf{v}_2} \mathbf{v}_2 = \frac{12}{11} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} = \frac{1}{33} \begin{bmatrix} 97 \\ 58 \\ 47 \end{bmatrix}.$$

and

$$\mathbf{z} = \mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} - \frac{1}{33} \begin{bmatrix} 97 \\ 58 \\ 47 \end{bmatrix} = \frac{1}{33} \begin{bmatrix} 2 \\ 8 \\ -14 \end{bmatrix}$$

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$$\text{proj}_W \mathbf{y} = \hat{\mathbf{y}} = \frac{\mathbf{y}^T \mathbf{u}_1}{\mathbf{u}_1^T \mathbf{u}_1} \mathbf{u}_1 + \dots + \frac{\mathbf{y}^T \mathbf{u}_p}{\mathbf{u}_p^T \mathbf{u}_p} \mathbf{u}_p$$

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- ▶ **Thm:** For all  $\mathbf{v} \in W$ ,  $\mathbf{v} \neq \hat{\mathbf{y}}$ ,

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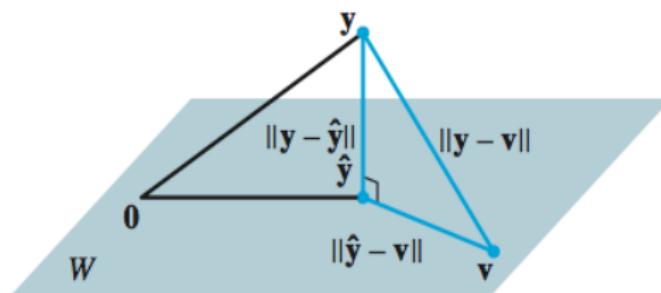
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**FIGURE 4** The orthogonal projection of  $\mathbf{y}$  onto  $W$  is the closest point in  $W$  to  $\mathbf{y}$ .

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PROOF: It is clear that  $\mathbf{z} \stackrel{\text{def}}{=} \mathbf{y} - \hat{\mathbf{y}} \in W^\perp$ . Then

$$\mathbf{y} - \mathbf{v} = \mathbf{z} + (\hat{\mathbf{y}} - \mathbf{v}),$$

with  $\mathbf{z} \in W^\perp, \hat{\mathbf{y}} - \mathbf{v} \in W$ . By Pythagorean Thm,

$$\|\mathbf{y} - \mathbf{v}\|^2 = \|\mathbf{z}\|^2 + \|\hat{\mathbf{y}} - \mathbf{v}\|^2 > \|\mathbf{z}\|^2. \quad \square$$