

Dimension of Vector Space: **Theorem 11**

LET: H be a subspace of finite-dimensional vector space V .

THEN: any linearly independent set $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_k\} \subseteq H$ can be expanded to a basis for H , with $\dim(H) \leq \dim(V)$.

Dimension of Vector Space: **Theorem 11**

LET: H be a subspace of finite-dimensional vector space V .

THEN: any linearly independent set $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_k\} \subseteq H$ can be expanded to a basis for H , with $\dim(H) \leq \dim(V)$.

PROOF: Assume $H \neq \{\mathbf{0}\}$ (see Book.)

(a) If $H = \mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$, then \mathcal{S} already basis for H .

Dimension of Vector Space: **Theorem 11**

LET: H be a subspace of finite-dimensional vector space V .

THEN: any linearly independent set $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_k\} \subseteq H$ can be expanded to a basis for H , with $\dim(H) \leq \dim(V)$.

PROOF: Assume $H \neq \{\mathbf{0}\}$ (see Book.)

- (a) If $H = \mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$, then \mathcal{S} already basis for H .
- (b) Otherwise there must be a vector $\mathbf{u}_{k+1} \in H$ but not in $\mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$.

Dimension of Vector Space: Theorem 11

LET: H be a subspace of finite-dimensional vector space V .

THEN: any linearly independent set $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_k\} \subseteq H$ can be expanded to a basis for H , with $\dim(H) \leq \dim(V)$.

PROOF: Assume $H \neq \{\mathbf{0}\}$ (see Book.)

- (a) If $H = \mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$, then \mathcal{S} already basis for H .
- (b) Otherwise there must be a vector $\mathbf{u}_{k+1} \in H$ but not in $\mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$.
- (c) Let $\widehat{\mathcal{S}} = \mathcal{S} \cup \{\mathbf{u}_{k+1}\}$.
- (d) Vectors in $\widehat{\mathcal{S}}$ must be linearly independent.

Dimension of Vector Space: **Theorem 11**

LET: H be a subspace of finite-dimensional vector space V .

THEN: any linearly independent set $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_k\} \subseteq H$ can be expanded to a basis for H , with $\dim(H) \leq \dim(V)$.

PROOF: Assume $H \neq \{\mathbf{0}\}$ (see Book.)

- (a) If $H = \mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$, then \mathcal{S} already basis for H .
- (b) Otherwise there must be a vector $\mathbf{u}_{k+1} \in H$ but not in $\mathbf{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_k\}$.
- (c) Let $\widehat{\mathcal{S}} = \mathcal{S} \cup \{\mathbf{u}_{k+1}\}$.
- (d) Vectors in $\widehat{\mathcal{S}}$ must be linearly independent.
- (e) Repeat steps (a-c) to continue expanding \mathcal{S} until it spans H and hence is a basis. **QED**

Dimension of Vector Space: **Theorem 12**

Let $V \neq \{\mathbf{0}\}$ be p -dimensional vector space, $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_p\} \subseteq H$. Then

$$\mathcal{S} \text{ is basis} \iff \mathcal{S} \text{ spans } V \iff \text{Vectors in } \mathcal{S} \text{ linearly independent.}$$

Dimension of Vector Space: **Theorem 12**

Let $V \neq \{\mathbf{0}\}$ be p -dimensional vector space, $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_p\} \subseteq H$. Then

\mathcal{S} is basis $\iff \mathcal{S}$ spans $V \iff$ Vectors in \mathcal{S} linearly independent.

PROOF: \mathcal{S} spans $V \implies \mathcal{S}$ is basis (rest in book)

- ▶ Since \mathcal{S} spans V , a subset of \mathcal{S} must be basis for V (**Thm 5**.)

Dimension of Vector Space: **Theorem 12**

Let $V \neq \{\mathbf{0}\}$ be p -dimensional vector space, $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_p\} \subseteq H$. Then

\mathcal{S} is basis $\iff \mathcal{S}$ spans $V \iff$ Vectors in \mathcal{S} linearly independent.

PROOF: \mathcal{S} spans $V \implies \mathcal{S}$ is basis (rest in book)

- ▶ Since \mathcal{S} spans V , a subset of \mathcal{S} must be basis for V (**Thm 5**.)
- ▶ $p = \dim V = \#$ of vectors in the subset. (by DEF.)

Dimension of Vector Space: **Theorem 12**

Let $V \neq \{\mathbf{0}\}$ be p -dimensional vector space, $\mathcal{S} = \{\mathbf{u}_1, \dots, \mathbf{u}_p\} \subseteq H$. Then

\mathcal{S} is basis $\iff \mathcal{S}$ spans $V \iff$ Vectors in \mathcal{S} linearly independent.

PROOF: \mathcal{S} spans $V \implies \mathcal{S}$ is basis (rest in book)

- ▶ Since \mathcal{S} spans V , a subset of \mathcal{S} must be basis for V (**Thm 5**.)
- ▶ $p = \dim V = \#$ of vectors in the subset. (by DEF.)
- ▶ Subset must be \mathcal{S} . **QED**

$$\begin{aligned}
 A &= [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{a}_4 \quad \mathbf{a}_5] \\
 &= \begin{bmatrix} 1 & 4 & 0 & 2 & -1 \\ 3 & 12 & 1 & 5 & 5 \\ 2 & 8 & 1 & 3 & 2 \\ 5 & 20 & 2 & 8 & 8 \end{bmatrix} \sim \begin{bmatrix} \boxed{1} & 4 & 0 & 2 & -1 \\ 0 & 0 & \boxed{1} & -1 & 8 \\ 0 & 0 & 0 & 0 & \boxed{-4} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.
 \end{aligned}$$

- Pivot columns are columns 1, 3, 5: $\text{Col } A = \mathbf{Span}(\mathbf{a}_1, \mathbf{a}_3, \mathbf{a}_5)$.

$$\begin{aligned}
 A &= [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{a}_4 \quad \mathbf{a}_5] \\
 &= \begin{bmatrix} 1 & 4 & 0 & 2 & -1 \\ 3 & 12 & 1 & 5 & 5 \\ 2 & 8 & 1 & 3 & 2 \\ 5 & 20 & 2 & 8 & 8 \end{bmatrix} \sim \begin{bmatrix} \boxed{1} & 4 & 0 & 2 & -1 \\ 0 & 0 & \boxed{1} & -1 & 8 \\ 0 & 0 & 0 & 0 & \boxed{-4} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.
 \end{aligned}$$

- ▶ Pivot columns are columns 1, 3, 5: $\text{Col } A = \mathbf{Span}(\mathbf{a}_1, \mathbf{a}_3, \mathbf{a}_5)$.
- ▶ Free columns are columns 2, 4: Letting $A\mathbf{x} = \mathbf{0}$ gives

$$\mathbf{x} = x_2 \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}. \implies \text{Nul } A = \mathbf{Span} \left(\begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right).$$

$$\begin{aligned}
 A &= [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{a}_4 \quad \mathbf{a}_5] \\
 &= \begin{bmatrix} 1 & 4 & 0 & 2 & -1 \\ 3 & 12 & 1 & 5 & 5 \\ 2 & 8 & 1 & 3 & 2 \\ 5 & 20 & 2 & 8 & 8 \end{bmatrix} \sim \begin{bmatrix} \boxed{1} & 4 & 0 & 2 & -1 \\ 0 & 0 & \boxed{1} & -1 & 8 \\ 0 & 0 & 0 & 0 & \boxed{-4} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.
 \end{aligned}$$

- ▶ Pivot columns are columns 1, 3, 5: $\text{Col } A = \mathbf{Span}(\mathbf{a}_1, \mathbf{a}_3, \mathbf{a}_5)$.
- ▶ Free columns are columns 2, 4: Letting $A\mathbf{x} = \mathbf{0}$ gives

$$\mathbf{x} = x_2 \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}. \implies \text{Nul } A = \mathbf{Span} \left(\begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right).$$

$\dim(\text{Col } A) = 3 = \# \text{ of pivots,}$
 $\dim(\text{Nul } A) = 2 = \# \text{ of free variables.}$

§4.6 Rank

DEF: Let $A \in \mathcal{R}^{m \times n}$. Then $\text{Row } A \stackrel{\text{def}}{=} \text{the span of row vectors of } A$.

$$\begin{aligned} \text{EX: ROW VECTOR FORM } A &= \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix} \\ &\sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \widehat{\mathbf{r}}_1 \\ \widehat{\mathbf{r}}_2 \\ \widehat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix}. \end{aligned}$$

§4.6 Rank

DEF: Let $A \in \mathcal{R}^{m \times n}$. Then $\text{Row } A \stackrel{\text{def}}{=} \text{the span of row vectors of } A$.

$$\begin{aligned} \text{EX: ROW VECTOR FORM } A &= \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix} \\ &\sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{\mathbf{r}}_1 \\ \hat{\mathbf{r}}_2 \\ \hat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix}. \end{aligned}$$

$$\hat{\mathbf{r}}_1 = \mathbf{r}_2, \quad \hat{\mathbf{r}}_2 = \mathbf{r}_1 + 2\hat{\mathbf{r}}_2, \quad \hat{\mathbf{r}}_3 = \mathbf{r}_4 - \hat{\mathbf{r}}_1 - 4\hat{\mathbf{r}}_2 \in \text{Span}(\mathbf{r}_1, \mathbf{r}_2, \mathbf{r}_3, \mathbf{r}_4).$$

§4.6 Rank

DEF: Let $A \in \mathcal{R}^{m \times n}$. Then $\text{Row } A \stackrel{\text{def}}{=} \text{the span of row vectors of } A$.

$$\begin{aligned} \text{EX: ROW VECTOR FORM } A &= \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix} \\ &\sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{\mathbf{r}}_1 \\ \hat{\mathbf{r}}_2 \\ \hat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix}. \end{aligned}$$

$$\hat{\mathbf{r}}_1 = \mathbf{r}_2, \quad \hat{\mathbf{r}}_2 = \mathbf{r}_1 + 2\hat{\mathbf{r}}_2, \quad \hat{\mathbf{r}}_3 = \mathbf{r}_4 - \hat{\mathbf{r}}_1 - 4\hat{\mathbf{r}}_2 \in \mathbf{Span}(\mathbf{r}_1, \mathbf{r}_2, \mathbf{r}_3, \mathbf{r}_4).$$

$$\implies \mathbf{Span}(\hat{\mathbf{r}}_1, \hat{\mathbf{r}}_2, \hat{\mathbf{r}}_3) = \mathbf{Span}(\mathbf{r}_1, \mathbf{r}_2, \mathbf{r}_3, \mathbf{r}_4) = \text{Row } A.$$

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On one hand,

Every elementary operation on A is a linear combination of rows in A

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On one hand,

Every elementary operation on A is a linear combination of rows in A
 \implies each row of B is a linear combination of rows in A .

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On one hand,

Every elementary operation on A is a linear combination of rows in A

\implies each row of B is a linear combination of rows in A .

$\implies \text{Row } B \subseteq \text{Row } A$.

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On the other hand,

Inverse of elementary operation is elementary operation

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On the other hand,

Inverse of elementary operation is elementary operation

\implies Every elementary operation on A is a linear combination of rows in B

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On the other hand,

Inverse of elementary operation is elementary operation

\implies Every elementary operation on A is a linear combination of rows in B

\implies each row of A is a linear combination of rows in B .

§4.6 Theorem 13

Let B be obtained from A with elementary operations $\implies \text{Row } A = \text{Row } B$.

PROOF: On the other hand,

Inverse of elementary operation is elementary operation

\implies Every elementary operation on A is a linear combination of rows in B

\implies each row of A is a linear combination of rows in B .

$\implies \text{Row } A \subseteq \text{Row } B. \quad \mathbf{QED}$

$$\begin{aligned}
 A &\stackrel{\text{def}}{=} [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{a}_4 \quad \mathbf{a}_5] = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix} \\
 &\sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{\mathbf{r}}_1 \\ \hat{\mathbf{r}}_2 \\ \hat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix} \cdot \boxed{\text{Row } A} = \mathbf{Span}(\hat{\mathbf{r}}_1, \hat{\mathbf{r}}_2, \hat{\mathbf{r}}_3)
 \end{aligned}$$

$$\begin{aligned}
 A \stackrel{\text{def}}{=} [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{a}_4 \quad \mathbf{a}_5] &= \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix} \\
 \sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{\mathbf{r}}_1 \\ \hat{\mathbf{r}}_2 \\ \hat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix} \cdot \boxed{\text{Row } A} = \mathbf{Span}(\hat{\mathbf{r}}_1, \hat{\mathbf{r}}_2, \hat{\mathbf{r}}_3)
 \end{aligned}$$

► Pivot columns 1, 2, 4 \implies $\boxed{\text{Col } A} = \mathbf{Span}(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_4)$.

$$A \stackrel{\text{def}}{=} [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{a}_4 \quad \mathbf{a}_5] = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix}$$

$$\sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{\mathbf{r}}_1 \\ \hat{\mathbf{r}}_2 \\ \hat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix}. \quad \boxed{\text{Row } A} = \mathbf{Span}(\hat{\mathbf{r}}_1, \hat{\mathbf{r}}_2, \hat{\mathbf{r}}_3)$$

- ▶ Pivot columns 1, 2, 4 $\implies \boxed{\text{Col } A} = \mathbf{Span}(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_4)$.
- ▶ free variable columns 3, 5. Let $A\mathbf{x} = \mathbf{0}$.

$$\mathbf{x} = x_3 \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -1 \\ -3 \\ 0 \\ 5 \\ 1 \end{bmatrix}, \quad \boxed{\text{Nul } A} = \mathbf{Span} \left(\begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 0 \\ 5 \\ 1 \end{bmatrix} \right)$$

$$A \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 & \mathbf{a}_4 & \mathbf{a}_5 \end{bmatrix} = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \\ \mathbf{r}_4 \end{bmatrix}$$

$$\sim \begin{bmatrix} \boxed{1} & 3 & -5 & 1 & 5 \\ 0 & \boxed{1} & -2 & 2 & -7 \\ 0 & 0 & 0 & \boxed{-4} & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \hat{\mathbf{r}}_1 \\ \hat{\mathbf{r}}_2 \\ \hat{\mathbf{r}}_3 \\ \mathbf{0} \end{bmatrix}. \quad \boxed{\text{Row } A} = \mathbf{Span}(\hat{\mathbf{r}}_1, \hat{\mathbf{r}}_2, \hat{\mathbf{r}}_3)$$

- ▶ Pivot columns 1, 2, 4 $\implies \boxed{\text{Col } A} = \mathbf{Span}(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_4)$.
- ▶ free variable columns 3, 5. Let $A\mathbf{x} = \mathbf{0}$.

$$\mathbf{x} = x_3 \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -1 \\ -3 \\ 0 \\ 5 \\ 1 \end{bmatrix}, \quad \boxed{\text{Nul } A} = \mathbf{Span} \left(\begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 0 \\ 5 \\ 1 \end{bmatrix} \right)$$

$$\boxed{\dim(\text{Col } A) + \dim(\text{Nul } A) = \# \text{ of columns}}$$

rank (A) $\stackrel{\text{def}}{=} \mathbf{dim} (\text{Col } A)$

$\text{rank}(A) \stackrel{\text{def}}{=} \text{dim}(\text{Col } A)$: The Rank Theorem

$$\text{rank}(A) + \text{dim}(\text{Nul } A) = \# \text{ of columns of } A.$$

PROOF:

$$\{\# \text{ of pivot cols}\} + \{\# \text{ of free variables}\} = \{\# \text{ of cols}\}.$$

rank (A) $\stackrel{\text{def}}{=} \mathbf{dim} (\text{Col } A)$

$\text{rank}(A) \stackrel{\text{def}}{=} \text{dim}(\text{Col } A)$: The Rank Theorem

$$\text{rank}(A) + \text{dim}(\text{Nul } A) = \# \text{ of columns of } A.$$

PROOF:

$$\begin{array}{ccc} \{\# \text{ of pivot cols}\} + \{\# \text{ of free variables}\} & = & \{\# \text{ of cols}\}. \\ \uparrow & & \uparrow \\ \text{rank} & & \text{dim}(\text{Nul } A) \end{array}$$

The Invertible Matrix Theorem (continued)

The Invertible Matrix Theorem (continued)

Let $A \in \mathcal{R}^{n \times n}$. Then following statements are equivalent.

- a. A is an invertible matrix.
- m. Columns of A form a basis for \mathcal{R}^n .
- p. $\text{rank}(A) = n$.
- r. $\dim(\text{Nul } A) = 0$.

§4.7 Change of Basis

§4.7 Change of Basis

Let $\mathbf{x} \in \mathcal{R}^n$, let \mathcal{B} and \mathcal{C} be two bases for \mathcal{R}^n .

- ▶ $[\mathbf{x}]_{\mathcal{B}}$ and $[\mathbf{x}]_{\mathcal{C}}$ are coordinates in bases \mathcal{B} and \mathcal{C} , respectively.
- ▶ How do $[\mathbf{x}]_{\mathcal{B}}$ and $[\mathbf{x}]_{\mathcal{C}}$ relate?

§4.7 Change of Basis

Let $\mathbf{x} \in \mathcal{R}^n$, let \mathcal{B} and \mathcal{C} be two bases for \mathcal{R}^n .

- ▶ $[\mathbf{x}]_{\mathcal{B}}$ and $[\mathbf{x}]_{\mathcal{C}}$ are coordinates in bases \mathcal{B} and \mathcal{C} , respectively.
- ▶ How do $[\mathbf{x}]_{\mathcal{B}}$ and $[\mathbf{x}]_{\mathcal{C}}$ relate?

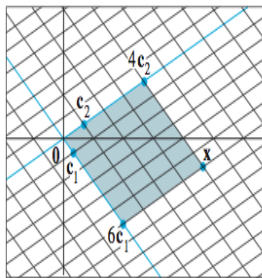
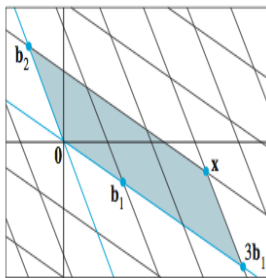
EX: Let $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, $[\mathbf{x}]_{\mathcal{C}} = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$. Then $[\mathbf{x}]_{\mathcal{C}} = [?] \cdot [\mathbf{x}]_{\mathcal{B}}$

§4.7 Change of Basis

Let $\mathbf{x} \in \mathcal{R}^n$, let \mathcal{B} and \mathcal{C} be two bases for \mathcal{R}^n .

- ▶ $[\mathbf{x}]_{\mathcal{B}}$ and $[\mathbf{x}]_{\mathcal{C}}$ are coordinates in bases \mathcal{B} and \mathcal{C} , respectively.
- ▶ How do $[\mathbf{x}]_{\mathcal{B}}$ and $[\mathbf{x}]_{\mathcal{C}}$ relate?

EX: Let $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, $[\mathbf{x}]_{\mathcal{C}} = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$. Then $[\mathbf{x}]_{\mathcal{C}} = [?] \cdot [\mathbf{x}]_{\mathcal{B}}$



Change of Basis: **Example**

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}.$$

Change of Basis: **Example**

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}.$$

with $\mathbf{b}_1 = 4\mathbf{c}_1 + \mathbf{c}_2$, and $\mathbf{b}_2 = -6\mathbf{c}_1 + \mathbf{c}_2$.

Suppose $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, find $[\mathbf{x}]_{\mathcal{C}}$.

Change of Basis: Example

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}.$$

with $\mathbf{b}_1 = 4\mathbf{c}_1 + \mathbf{c}_2$, and $\mathbf{b}_2 = -6\mathbf{c}_1 + \mathbf{c}_2$.

Suppose $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, find $[\mathbf{x}]_{\mathcal{C}}$.

SOLUTION: Basis relations are

$$[\mathbf{b}_1]_{\mathcal{C}} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}, \quad [\mathbf{b}_2]_{\mathcal{C}} = \begin{bmatrix} -6 \\ 1 \end{bmatrix}.$$

Change of Basis: Example

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}.$$

with $\mathbf{b}_1 = 4\mathbf{c}_1 + \mathbf{c}_2$, and $\mathbf{b}_2 = -6\mathbf{c}_1 + \mathbf{c}_2$.

Suppose $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, find $[\mathbf{x}]_{\mathcal{C}}$.

SOLUTION: Basis relations are

$$[\mathbf{b}_1]_{\mathcal{C}} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}, \quad [\mathbf{b}_2]_{\mathcal{C}} = \begin{bmatrix} -6 \\ 1 \end{bmatrix}.$$

$$\begin{aligned} [\mathbf{x}]_{\mathcal{C}} &= [3\mathbf{b}_1 + \mathbf{b}_2]_{\mathcal{C}} = 3[\mathbf{b}_1]_{\mathcal{C}} + [\mathbf{b}_2]_{\mathcal{C}} \\ &= [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}] \begin{bmatrix} 3 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 4 & -6 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \end{bmatrix} \end{aligned}$$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

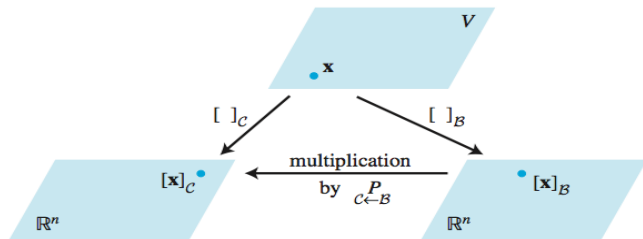


FIGURE 2 Two coordinate systems for V .

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

PROOF: Let $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n$ so that $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}.$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

PROOF: Let $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n$ so that $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}.$

$$[\mathbf{x}]_{\mathcal{C}} = [\alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n]_{\mathcal{C}}$$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

PROOF: Let $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n$ so that $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}.$

$$[\mathbf{x}]_{\mathcal{C}} = [\alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n]_{\mathcal{C}} = \alpha_1 [\mathbf{b}_1]_{\mathcal{C}} + \dots + \alpha_n [\mathbf{b}_n]_{\mathcal{C}}$$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

PROOF: Let $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n$ so that $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}.$

$$\begin{aligned} [\mathbf{x}]_{\mathcal{C}} &= [\alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n]_{\mathcal{C}} = \alpha_1 [\mathbf{b}_1]_{\mathcal{C}} + \dots + \alpha_n [\mathbf{b}_n]_{\mathcal{C}} \\ &= [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}] \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} \end{aligned}$$

Change of Basis

Consider two bases for vector space V :

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}, \quad \mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\}.$$

change-of-coordinates matrix: $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} \stackrel{\text{def}}{=} [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}].$

Thm: For any vector $\mathbf{x} \in V$, $[\mathbf{x}]_{\mathcal{C}} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}}$

PROOF: Let $\mathbf{x} = \alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n$ so that $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}.$

$$\begin{aligned} [\mathbf{x}]_{\mathcal{C}} &= [\alpha_1 \mathbf{b}_1 + \dots + \alpha_n \mathbf{b}_n]_{\mathcal{C}} = \alpha_1 [\mathbf{b}_1]_{\mathcal{C}} + \dots + \alpha_n [\mathbf{b}_n]_{\mathcal{C}} \\ &= [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}, \dots, [\mathbf{b}_n]_{\mathcal{C}}] \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} = \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} [\mathbf{x}]_{\mathcal{B}} \end{aligned}$$

EX: Consider two bases for \mathcal{R}^2 : $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$, $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$.

EX: Consider two bases for \mathcal{R}^2 : $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$, $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$.

with $\mathbf{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$, $\mathbf{b}_2 = \begin{bmatrix} -5 \\ -1 \end{bmatrix}$, $\mathbf{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$, $\mathbf{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$.

Find $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} = [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}]$

EX: Consider two bases for \mathcal{R}^2 : $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$, $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$.

with $\mathbf{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$, $\mathbf{b}_2 = \begin{bmatrix} -5 \\ -1 \end{bmatrix}$, $\mathbf{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$, $\mathbf{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$.

Find $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} = [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}]$

SOLUTION: Let $[\mathbf{b}_1]_{\mathcal{C}} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$. Then

$$\mathbf{b}_1 = \alpha_1 \mathbf{c}_1 + \alpha_2 \mathbf{c}_2$$

EX: Consider two bases for \mathcal{R}^2 : $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$, $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$.

with $\mathbf{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$, $\mathbf{b}_2 = \begin{bmatrix} -5 \\ -1 \end{bmatrix}$, $\mathbf{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$, $\mathbf{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$.

Find $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} = [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}]$

SOLUTION: Let $[\mathbf{b}_1]_{\mathcal{C}} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$. Then

$$\mathbf{b}_1 = \alpha_1 \mathbf{c}_1 + \alpha_2 \mathbf{c}_2 = \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$$

EX: Consider two bases for \mathcal{R}^2 : $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$, $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2\}$.

with $\mathbf{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$, $\mathbf{b}_2 = \begin{bmatrix} -5 \\ -1 \end{bmatrix}$, $\mathbf{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$, $\mathbf{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$.

Find $\mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} = [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}]$

SOLUTION: Let $[\mathbf{b}_1]_{\mathcal{C}} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$. Then

$$\mathbf{b}_1 = \alpha_1 \mathbf{c}_1 + \alpha_2 \mathbf{c}_2 = \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} \implies \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \end{bmatrix}^{-1} \mathbf{b}_1.$$

therefore $[\mathbf{b}_1]_{\mathcal{C}} = \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \end{bmatrix}^{-1} \mathbf{b}_1$, and $[\mathbf{b}_2]_{\mathcal{C}} = \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \end{bmatrix}^{-1} \mathbf{b}_2$.

$$\begin{aligned} \mathcal{C} \stackrel{\mathbf{P}}{\leftarrow} \mathcal{B} &= [[\mathbf{b}_1]_{\mathcal{C}}, [\mathbf{b}_2]_{\mathcal{C}}] = \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 3 \\ -4 & -5 \end{bmatrix}^{-1} \begin{bmatrix} -9 & -5 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 6 & 4 \\ -5 & -3 \end{bmatrix} \end{aligned}$$