

Final Exam in a nutshell

- ▶ **time:** Tuesday, May 14, from 7:00-10:00PM, in Pimentel 1.
 - ▶ **DSP time:** Tuesday, May 14, from 4:00-10:00PM in 1015 Evans Hall, with DSP letter only.
- ▶ **scope:** every section covered in class.
 - ▶ Except PCA in Chapter 7, Heat equations in 2 dimensions.
 - ▶ 4 Questions from Part I, 2 Questions from Part II.
- ▶ **cheat sheet:** one-page/one-sided cheat sheet.
- ▶ **background:**
 - ▶ Basic knowledge integrating simple functions (exponential, trigonometric functions, polynomials)
 - ▶ Basic trigonometric identities.
 - ▶ Basic knowledge of complex numbers.
- ▶ **OH:** M: 12:15-1:00PM, 4:10-5:30PM, W: 4:10-5:30PM, F: 12:30-2:00PM.

Formula for final grade

- ▶ Weekly home work sets;
Count best 10, total 15 points.
- ▶ Weekly Quizzes;
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- ▶ Two midterm exams:
the worse is 15 points, the better 25 points.
- ▶ 1 final exam, 30 points.

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- ▶ 1 final exam, 30 points.
- ▶ **If you miss one midterm, your other midterm and the final will be worth 30 and 40 points, respectively.**

Grade Scale

- ▶ **A-** to **A+**: at least 85 points;
- ▶ **B-** to **B+**: between 70 and 85 points;
- ▶ **C-** to **C+**: between 60 and 70 points;
- ▶ **D**: between 55 and 60 points;
- ▶ **F**: less than 55 points.

Typically over $2/3$ of class receives *B* level grades or above.

How to review

- ▶ No need to go beyond the book
- ▶ Best to go beyond homework: practice your skills with exercises in the book
- ▶ Exam problems are either taken or modified from the book.

Problem distribution

- ▶ One question from Chapter 1 through Chapter 3: Linear algebra, Matrix algebra, Determinants
- ▶ One question from Chapter 4: Vector Spaces
- ▶ One question from Chapter 6: Least Squares
- ▶ One question from Chapters 5 and 7: Eigenvalues and SVD
- ▶ One question from Chapters 4 and 9: Linear ODEs
- ▶ One question from Chapter 10: Fourier Analysis and Heat equation

Sample Problem 1: (Problem 17, p. 90)

Explain why a set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ in \mathcal{R}^5 must be linearly independent when $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly independent and $\mathbf{v}_4 \notin \mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.

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SOLUTION: We prove the claim by contradiction. Assume that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ in \mathcal{R}^5 was linearly dependent. Then there would be constants c_1, \dots, c_4 , not all of which were 0, such that

$$c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3 + c_4 \mathbf{v}_4 = \mathbf{0}. \quad (\ell)$$

There are two cases to consider in equation (ℓ)

- ▶ If $c_4 = 0$, then (ℓ) would become

$$c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3 = \mathbf{0},$$

for some constants c_1, c_2, c_3 , not all of which were 0, which contradicts the assumption that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly independent.

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SOLUTION: We prove the claim by contradiction. Assume that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ in \mathcal{R}^5 was linearly dependent. Then there would be constants c_1, \dots, c_4 , not all of which were 0, such that

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There are two cases to consider in equation (ℓ)

- ▶ If $c_4 \neq 0$, then (ℓ) would become

$$\mathbf{v}_4 = -\frac{1}{c_4} (c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3),$$

which contradicts the assumption that $\mathbf{v}_4 \notin \mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.

Thus equation (ℓ) can't be true, meaning $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ must be linearly independent. \square

Sample Problem 2: (Problem 5, p. 265)

Consider the polynomials

$$\mathbf{p}_1(t) = 1 + t, \quad \mathbf{p}_2(t) = 1 - t, \quad \mathbf{p}_3(t) = 4,$$

$$\mathbf{p}_4(t) = t + t^2, \quad \mathbf{p}_5(t) = 1 + 2t + t^2.$$

Let H be the subspace of \mathcal{P}_3 spanned by the set $\mathcal{S} = \{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3, \mathbf{p}_4, \mathbf{p}_5\}$. Construct a basis for H .

Sample Problem 2: (Problem 5, p. 265)

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$$\begin{aligned}\mathbf{p}_1(t) &= 1 + t, & \mathbf{p}_2(t) &= 1 - t, & \mathbf{p}_3(t) &= 4, \\ \mathbf{p}_4(t) &= t + t^2, & \mathbf{p}_5(t) &= 1 + 2t + t^2.\end{aligned}$$

Let H be the subspace of \mathcal{P}_3 spanned by the set $\mathcal{S} = \{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3, \mathbf{p}_4, \mathbf{p}_5\}$. Construct a basis for H .

SOLUTION: We will construct a basis for H step-by-step:

- ▶ Since $\mathbf{p}_1 \neq 0$, it is linearly independent.
- ▶ \mathbf{p}_1 and \mathbf{p}_2 are not multiples of each other, so $\{\mathbf{p}_1, \mathbf{p}_2\}$ is linearly independent.
- ▶ $\mathbf{p}_3 = 2\mathbf{p}_1 + 2\mathbf{p}_2$, so we ignore \mathbf{p}_3 for basis construction.
- ▶ \mathbf{p}_4 is not a linear combination of \mathbf{p}_1 and \mathbf{p}_2 since neither contains the monomial t^2 . so $\{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_4\}$ is linearly independent.
- ▶ $\mathbf{p}_5 = \mathbf{p}_1 + \mathbf{p}_4$, so we ignore \mathbf{p}_5 for basis construction.

Thus one basis for H is $\{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_4\}$. \square

Sample Problem 3: (Problem 19, p. 369)

Let $A \in \mathcal{R}^{m \times n}$. Show that $\text{NUL } A = \text{NUL } A^T A$.

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Let $A \in \mathcal{R}^{m \times n}$. Show that $\text{NUL } A = \text{NUL } A^T A$.

SOLUTION: We will show that $\text{NUL } A \subseteq \text{NUL } A^T A$ and $\text{NUL } A^T A \subseteq \text{NUL } A$ so they must be the same set.

- ▶ Let $\mathbf{x} \in \text{NUL } A$ so that $A\mathbf{x} = \mathbf{0}$. This means $A^T A\mathbf{x} = \mathbf{0}$, or that $\mathbf{x} \in \text{NUL } A^T A$. Thus, $\text{NUL } A \subseteq \text{NUL } A^T A$.
- ▶ Let $\mathbf{x} \in \text{NUL } A^T A$ so that $A^T A\mathbf{x} = \mathbf{0}$. This means $\mathbf{x}^T A^T A\mathbf{x} = 0$, or that $\|A\mathbf{x}\|^2 = 0$. Therefore $A\mathbf{x} = \mathbf{0}$ and $\mathbf{x} \in \text{NUL } A$. Thus, $\text{NUL } A^T A \subseteq \text{NUL } A$ \square .

Sample Problem 4: Compute the SVD

$$A = \begin{pmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{pmatrix}. \text{ Eigenvalues of } A^T A: \lambda_1 = 360, \lambda_2 = 90, \lambda_3 = 0,$$

$$\text{unit eigenvectors } \mathbf{v}_1 = \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \quad \mathbf{v}_2 = \frac{1}{3} \begin{pmatrix} -2 \\ -1 \\ 2 \end{pmatrix}, \quad \mathbf{v}_3 = \frac{1}{3} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}.$$

$$A\mathbf{v}_1 = \sqrt{360}\mathbf{u}_1, \quad A\mathbf{v}_2 = \sqrt{90}\mathbf{u}_2, \quad , A\mathbf{v}_3 = \mathbf{0}.$$

$$\text{where } \mathbf{u}_1 = \frac{1}{\sqrt{10}} \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \quad \mathbf{u}_2 = \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ -3 \end{pmatrix}.$$

Putting together

$$A(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3) = (\sqrt{360}\mathbf{u}_1, \sqrt{90}\mathbf{u}_2, \mathbf{0}) = (\mathbf{u}_1, \mathbf{u}_2) \begin{pmatrix} \sqrt{360} & 0 & 0 \\ 0 & \sqrt{90} & 0 \end{pmatrix}.$$

$$\text{Therefore } A = (\mathbf{u}_1, \mathbf{u}_2) \begin{pmatrix} \sqrt{360} & 0 & 0 \\ 0 & \sqrt{90} & 0 \end{pmatrix} (\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)^T.$$

Sample Problem 5: Problem 7, p. 191

Find a general solution to the ODE:

$$y'' + 4y' + 4y = e^{-2t} \ln t. \quad (\ell)$$

SOLUTION: The homogeneous equation implied by (ℓ) is

$$y'' + 4y' + 4y = 0. \quad (\ell_1)$$

The auxiliary equation to (ℓ_1) is $r^2 + 4r + 4 = 0$, which has a double root $r = -2$. Therefore two linearly independent solutions to (ℓ_1) are $y_1(t) = e^{-2t}$ and $y_2(t) = t e^{-2t}$. Their Wronskian is

$$\begin{aligned} \mathbf{Wron} [y_1, y_2](t) &= \mathbf{det} \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\ &= \mathbf{det} \begin{vmatrix} e^{-2t} & t e^{-2t} \\ -2e^{-2t} & e^{-2t} - 2t e^{-2t} \end{vmatrix} = e^{-4t}. \end{aligned}$$

Sample Problem 5: Problem 7, p. 191

Find a general solution to the ODE:

$$y'' + 4y' + 4y = e^{-2t} \ln t. \quad (\ell)$$

SOLUTION: The homogeneous equation implied by (ℓ) has two linearly independent solutions $y_1(t) = e^{-2t}$ and $y_2(t) = t e^{-2t}$. Their Wronskian is

$$\mathbf{Wron} [y_1, y_2](t) = e^{-4t}.$$

Now we seek a particular solution to (ℓ) in the form

$$y_p(t) = v_1(t) y_1(t) + v_2(t) y_2(t), \quad \text{where}$$

$$v_1(t) = - \int^t \frac{y_2(\tau) e^{-2\tau} \ln \tau d\tau}{\mathbf{Wron} [y_1, y_2](\tau)} = - \int^t \tau \ln \tau d\tau = c_1 - \frac{t^2}{2} \ln \frac{t}{\sqrt{e}},$$

$$v_2(t) = \int^t \frac{y_1(\tau) e^{-2\tau} \ln \tau d\tau}{\mathbf{Wron} [y_1, y_2](\tau)} = \int^t \ln \tau d\tau = c_2 + t \ln \frac{t}{e}.$$

General solution is $y(t) = (c_1 + c_2 t) e^{-2t} + \left(\frac{t^2}{2} \ln \frac{t}{e\sqrt{e}} \right) e^{-2t}$.

Sample Problem 6

- ▶ Compute the Fourier cosine series for the given function $f(x) = \mathbf{\sin}(x)$ on $[0, \pi]$.
- ▶ Find a formal solution to

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < \pi, \quad t > 0.$$

$$u(x, 0) = \mathbf{\sin}(x) \quad \forall x \in [0, \pi]; \quad \frac{\partial u}{\partial x}(0, t) = 0 = \frac{\partial u}{\partial x}(\pi, t) \quad \forall t > 0.$$

Sample Problem 6

- ▶ Compute the Fourier cosine series for the given function

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SOLUTION:

- ▶ The Fourier cosine series

$$\tilde{S}(x) = \frac{\tilde{a}_0}{2} + \sum_{n=1}^{\infty} \tilde{a}_n \mathbf{\cos}(nx), \quad \text{where for } n = 0, 1, \dots,$$

$$\tilde{a}_n = \frac{2}{\pi} \int_0^{\pi} \mathbf{\sin}(x) \mathbf{\cos}(nx) dx = \begin{cases} 0, & \text{if } n \text{ is odd,} \\ -\frac{4}{\pi(n+1)(n-1)}, & \text{if } n \text{ is even,} \end{cases}$$

$$\tilde{S}(x) = \frac{2}{\pi} - \frac{4}{\pi} \sum_{n=1}^{\infty} \frac{\mathbf{\cos}(2nx)}{(2n+1)(2n-1)}.$$

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SOLUTION:

- ▶ The formal solution to heat equation is

$$u(x, t) \sim \frac{2}{\pi} - \frac{4}{\pi} \sum_{n=1}^{\infty} \frac{\mathbf{\cos}(2nx)}{(2n+1)(2n-1)} e^{-4n^2 t}.$$