

3. Let V denote the set of all solutions to the system of linear equations

$$\begin{aligned}x_1 - x_2 + 2x_4 &= 0 \\ 2x_1 - x_2 - x_3 + 3x_4 &= 0.\end{aligned}$$

1

Extend $\{(0, 2, 1, 1)\}$ to a basis of V .

Row reductions do everything! We start from $\begin{pmatrix} 1 & -1 & 0 & 2 \\ 2 & -1 & -1 & 3 \end{pmatrix}$.

$R_2 \rightarrow R_2 - 2R_1$

$$\rightarrow \begin{pmatrix} 1 & -1 & 0 & 2 \\ 0 & 1 & -1 & -1 \end{pmatrix} \xrightarrow{R_1 \rightarrow R_1 + R_2} \begin{pmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & -1 & -1 \end{pmatrix} \text{ RREF.}$$

As 3rd, 4th col's are non-pivot, let x_3, x_4 be arbitrary real #'s.

1st row: $x_1 - x_3 + x_4 = 0 \Rightarrow x_1 = x_3 - x_4$.

2nd row: $x_2 - x_3 - x_4 = 0 \Rightarrow x_2 = x_3 + x_4$.

All together: $\begin{pmatrix} x_1 \\ \vdots \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} x_3 - x_4 \\ x_3 + x_4 \\ x_3 \\ x_4 \end{pmatrix}$

$$V = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ and } \dim V = 2.$$

$$= x_3 \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

Sanity check: $\begin{pmatrix} 0 \\ 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$.

So, $\left\{ \begin{pmatrix} 0 \\ 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}$ works.

2. Compute the determinant of $A+tI$, where I is the 4×4 identity matrix, $A = \begin{pmatrix} 0 & 0 & 0 & a_0 \\ -1 & 0 & 0 & a_1 \\ 0 & -1 & 0 & a_2 \\ 0 & 0 & -1 & a_3 \end{pmatrix}$, **2** $a_1 + a_2 t + a_3 t^2 + t^3$

and $t, a_i \in F$ are scalars.

① $\det \begin{pmatrix} t & & & \\ -1 & t & & \\ & -1 & t & \\ & & -1 & a_3+t \end{pmatrix}$ row operations? $\equiv \det \begin{pmatrix} t & & & \\ 0 & -1 & 0 & (a_2+a_3t+t^2) \\ 0 & 0 & -1 & a_3+t \end{pmatrix}$ $R_2 \rightarrow R_2 + t \cdot R_3$ $\equiv \det \begin{pmatrix} t & & & \\ -1 & 0 & 0 & \\ & -1 & 0 & \\ & & -1 & \end{pmatrix}$

$R_1 \rightarrow R_1 + t \cdot R_2$
 $= \det \begin{pmatrix} 0 & 0 & 0 & \square \\ -1 & 0 & 0 & * \\ 0 & -1 & 0 & * \\ 0 & 0 & -1 & * \end{pmatrix} = a_0 + t \cdot (a_1 + a_2 t + a_3 t^2 + t^3)$
 $= a_0 + a_1 t + a_2 t^2 + a_3 t^3 + t^4$

② $\det \begin{pmatrix} t & & & a_0 \\ -1 & t & & a_1 \\ & -1 & t & a_2 \\ & & -1 & a_3+t \end{pmatrix}$ cofactor expansion: first row
 $t \cdot \det \begin{pmatrix} t & 0 & a_1 \\ -1 & t & a_2 \\ 0 & -1 & a_3+t \end{pmatrix} - a_0 \det \begin{pmatrix} -1 & t & \\ 0 & -1 & t \\ 0 & 0 & -1 \end{pmatrix}$
 $= t \cdot \det \begin{pmatrix} t & 0 & a_1 \\ -1 & t & a_2 \\ 0 & -1 & a_3+t \end{pmatrix} + a_1 \cdot \det \begin{pmatrix} -1 & t \\ 0 & -1 \end{pmatrix} = t [t \cdot (t^2 + a_3 t + a_2) + a_1] + a_0 = t^4 + a_3 t^3 + a_2 t^2 + a_1 t + a_0$

1. Let $A, B \in M_{n \times n}(\mathbb{R})$ be matrices such that $AB = -BA$. Prove that if n is odd, then either A or B is not invertible. When n is even, determine whether this is true. If so, give a proof. If not, provide a counterexample.

3 Poll

Fact. ① A is invertible if and only if $\det A \neq 0$.

② $\det(c \cdot A) = c^n \cdot \det(A)$ if $A: n \times n$. & $\det(AB) = \det(A) \det(B)$

Sol'n. As $AB = -BA$, $\det(AB) = \det(-BA) = (-1)^n \cdot \det(BA)$
 $\det A \cdot \det B = -1 \cdot \det B \cdot \det A$ b/c n : odd.

So, $\det A \cdot \det B = 0$ and so A or B has det zero $\Leftrightarrow A$ or B is not invertible.

$n=2$ case: try to find conditions for a counterexample!

Suppose A, B : invertible $AB = -BA \Rightarrow B^{-1}AB = -A$. ($A \sim -A$)
 $\text{tr}(A) = \text{tr}(-A) = -\text{tr}(A) \Rightarrow \text{tr}(A) = 0$.

Try $A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$B^{-1} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} B = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$

$B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ works.

2. Let $B \in M_{n \times n}(F)$ be fixed, and let $T_B : M_{n \times n}(F) \rightarrow M_{n \times n}(F)$ be the linear transformation defined by $T_B(A) = AB - BA$. Compute $\det([T_B]_\beta)$, where β is any basis of $M_{n \times n}(F)$.

3 Poll

β does not really matter! (b/c $[T_B]_\alpha = ([I]_\alpha)^{-1} [T_B]_\beta [I]_\alpha$)

Fact: T is an isomorphism if and only if $[T]_\beta$ is invertible (for any basis β).

Why? (\Rightarrow) T^{-1} exists. So, $T \circ T^{-1} = I$ and
 $[T]_\beta \cdot [T^{-1}]_\beta = [T \circ T^{-1}]_\beta = [I]_\beta = I_{n \times n}$.

Sol'n. If T_B is not an isom, then $\det([T_B]_\beta) = 0$.

If $\ker(T_B)$ is not zero, then $\det([T_B]_\beta) = 0$. (b/c $T_B : V \rightarrow V$).

(\Leftarrow)
 $0 \neq I_{n \times n}$ (b/c $I_{n \times n} B - B I_{n \times n} = B - B = 0$).

5

1. (True/False Jeopardy) Supply convincing reasoning for your answer.

- (a) T F For $c \in F$ and $A \in M_{n \times n}(F)$, we have $\det(cA) = c \det(A)$.
- (b) T F Let $A, B \in M_{n \times n}(F)$. Then $\det(A + B) = \det(A) + \det(B)$.
- (c) T F Let V be a finite-dimensional vector space, and let $T : V \rightarrow V$ be a linear transformation. If β, β' are two bases of V , then $\det([T]_{\beta}) = \det([T]_{\beta'})$.
- (d) T F Let $A \in M_{m \times n}(F)$. If $m > n$, then ~~there exists some $b \in F^m$ such that $Ax = b$ is inconsistent.~~
- (e) T F Let $A \in M_{m \times n}(F)$. If $m < n$, then there exists some $b \in F^m$ such that $Ax = b$ has a unique solution.

a. FALSE
 c^n not c .

b. Use 0 and 1 OR $B = ? A$
 FALSE.
 $B = A$ $\det(2B) = 2 \det(B)$
 not true.

c. $[T]_{\beta} = ? [T]_{\beta'}$
 True.
 Similar \Rightarrow det same.

Inverse
 $[I]_{\beta}^{-1}$ $[I]_{\beta'}^{-1}$
 \downarrow \downarrow

d. A defines a linear map $\mathbb{R}^n \rightarrow \mathbb{R}^m$.
 $A: F^n \rightarrow F^m$ (smaller to larger)
 $\Rightarrow \text{im } A \neq F^m$.
 True. (b/c by dim. thm. $\dim \ker A + \text{rk } A = n$
 $\Rightarrow \text{rk } A \leq n < m = \dim F^m$)

e. $Ax = b$ unique sol'n.
 What can you say about
 $Ax = 0$?
 $Ax = 0$ has a unique sol'n.
 $A: \mathbb{R}^n \rightarrow F^m$
 \Downarrow
 A is I.I.
 $\ker A = 0$.

2. Let $A \in M_{m \times n}(\mathbb{R})$, and suppose $m > n$. We know that $Ax = b$ does not always have a solution for $b \in \mathbb{R}^m$. Prove that nonetheless, $A^t Ax = A^t b$ always has a solution.

4 Math 54 Review

Fun fact: $A^t Ax = 0$, then in fact $Ax = 0$.

Why? ① Note that, given $v = (v_1, \dots, v_m) \in \mathbb{R}^m$, $v^t \cdot v$ as a matrix multiplication column vector is simply $v_1^2 + \dots + v_m^2$.

② Now, suppose that $A^t Ax = 0$. Then, we can multiply x^t on the left to get $x^t A^t Ax = x^t \cdot 0 = 0$. Putting $v = Ax$, we get $v^t v = 0$ and this shows that $v_1 = \dots = v_m = 0$, so $v = 0$ and $Ax = 0$.

So what? Obviously, if $x \in \ker A$, then $Ax = 0 \Rightarrow A^t Ax = 0 \Rightarrow x \in \ker A^t A$. Combining this with the above "fun fact", we get

$$\ker A = \ker A^t A. \quad \text{But } A: \mathbb{R}^n \rightarrow \mathbb{R}^m \text{ and } A^t A: \mathbb{R}^n \rightarrow \mathbb{R}^n.$$

Hence, by the dimension theorem, we get $\text{rk } A = n - \dim \ker A = n - \dim \ker A^t A = \text{rk } A^t A$.

However, $\text{im } A^t A \subseteq \text{im } A^t$ obviously, so $\text{rk } A^t A \leq \text{rk } A^t$. In particular, $\text{rk } A \leq \text{rk } A^t$.

Doing the same argument to A^t , we get $\text{rk } A^t \leq \text{rk } (A^t)^t = \text{rk } A$.

Therefore $\text{rk } A = \text{rk } A^t A = \text{rk } A^t$, that is, $\dim \text{im } A^t A = \dim \text{im } A^t$.

Hence, $\text{im } A^t A = \text{im } A^t$. \square